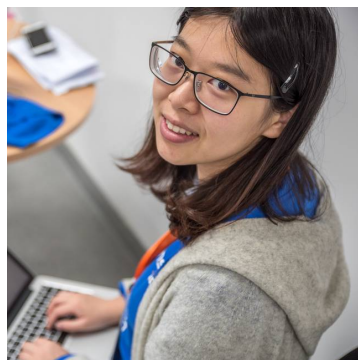


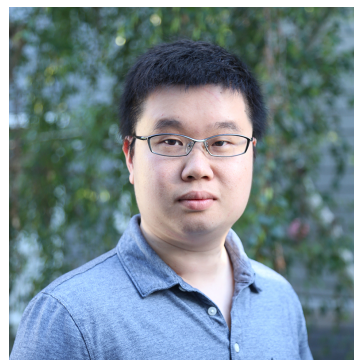
# Delving Deeper into Anti-aliasing in ConvNets



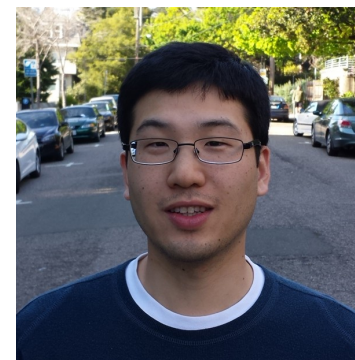
Xueyan Zou



Fanyi Xiao



Zhiding Yu



Yong Jae Lee

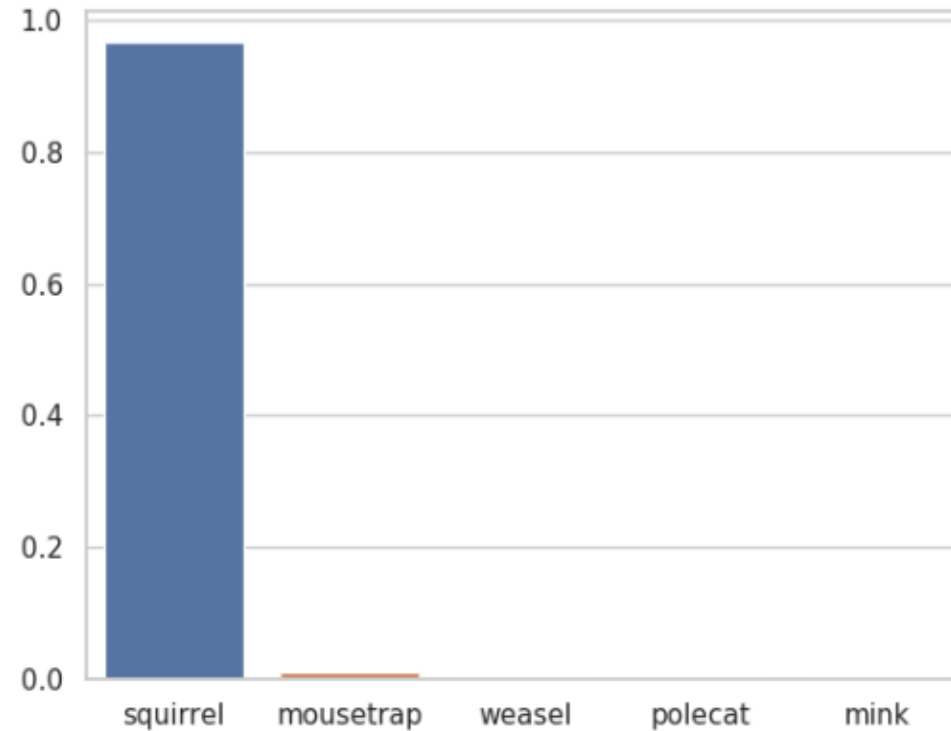


**UCDAVIS**



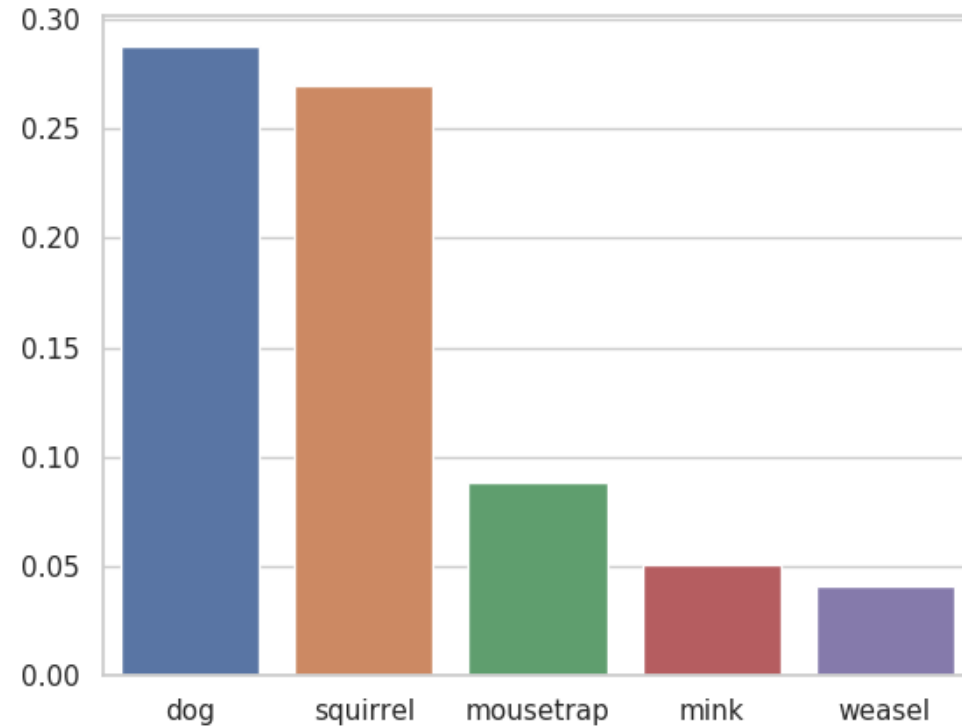
**nVIDIA.**

# Shift Inconsistency in Image Classification



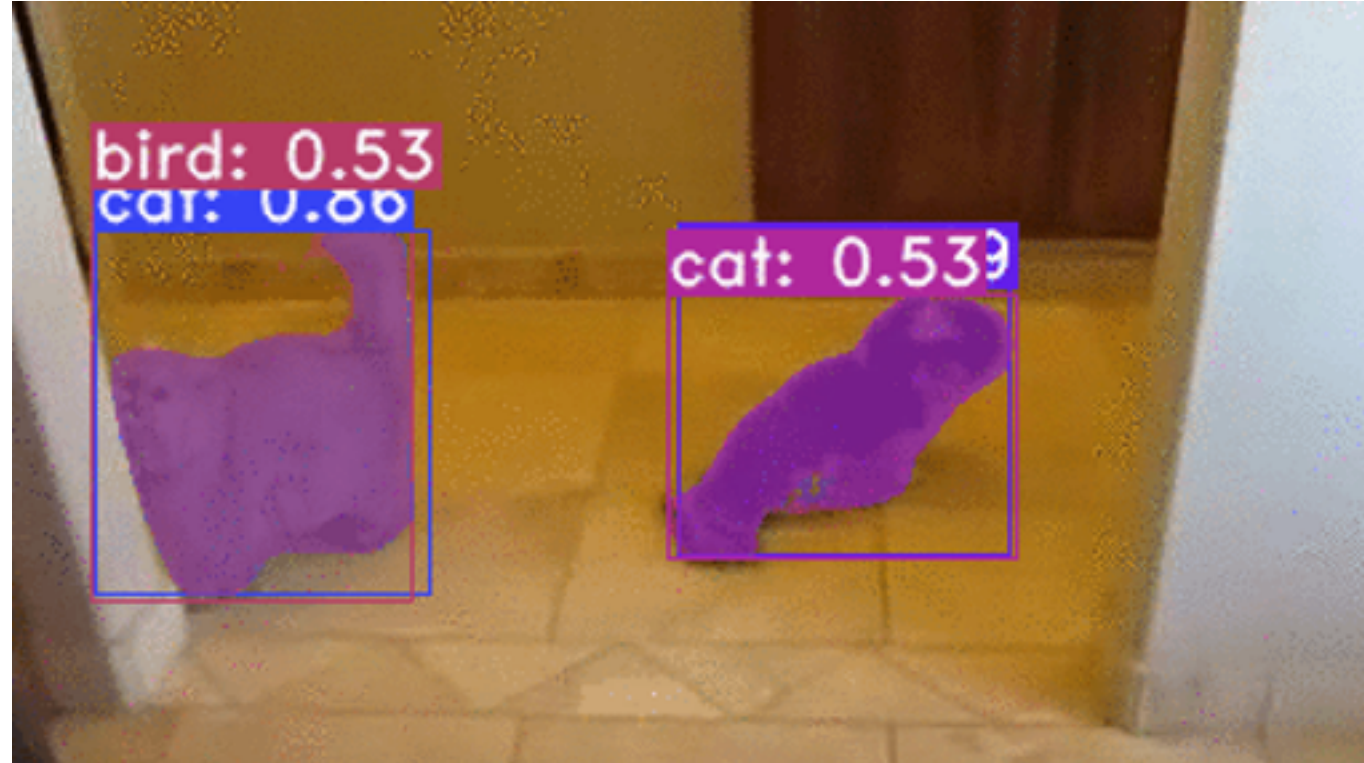
Classifier could correctly classify the image as squirrel

# Shift Inconsistency in Image Classification



With a tiny shift, output prediction changes dramatically

# Shift Inconsistency in Instance Segmentation



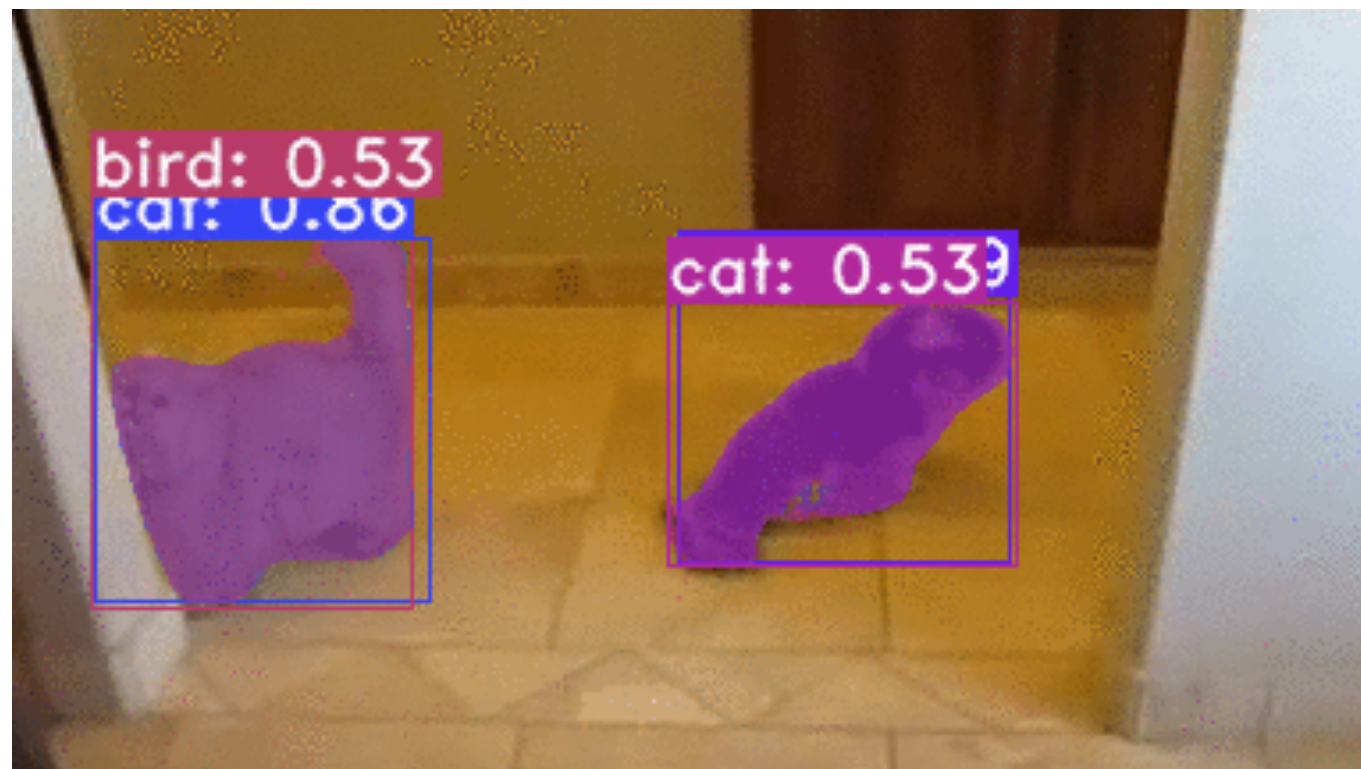
This phenomenon holds for instance segmentation

[1] Making Convolution Network Shift and Invariant Again. Zhang. *ICML 2019*

[2] Do Image Classifiers Generalize Across Time? Shankar et al. *arXiv 2019*



# Shift Inconsistency in Instance Segmentation

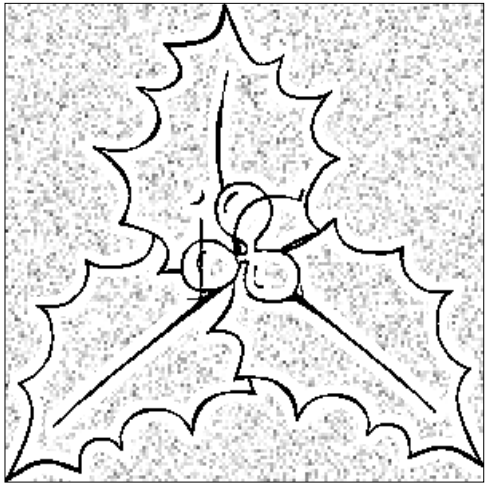


Classifier hovers the decision between cat and dog

[1] Making Convolution Network Shift and Invariant Again. Zhang. *ICML 2019*

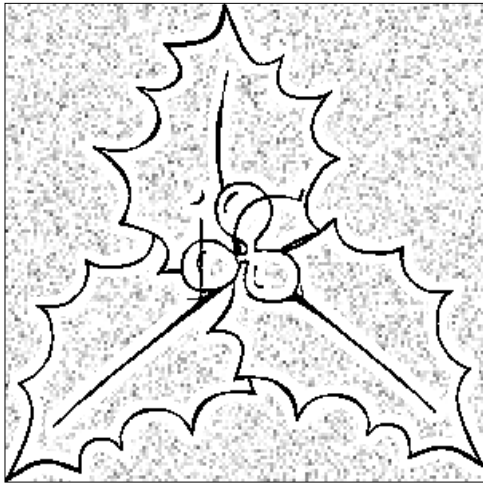
[2] Do Image Classifiers Generalize Across Time? Shankar et al. *arXiv 2019*

# Aliasing

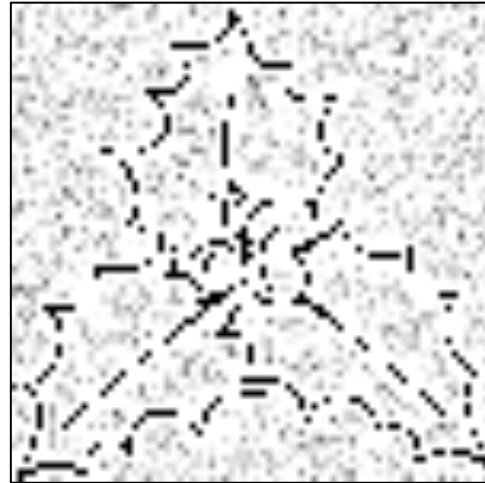


(a) Input

# Aliasing

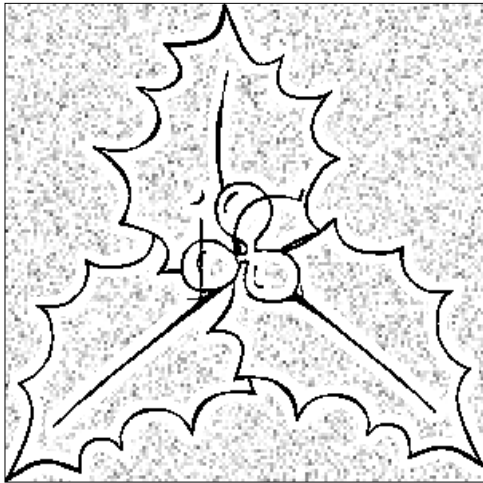


(a) Input

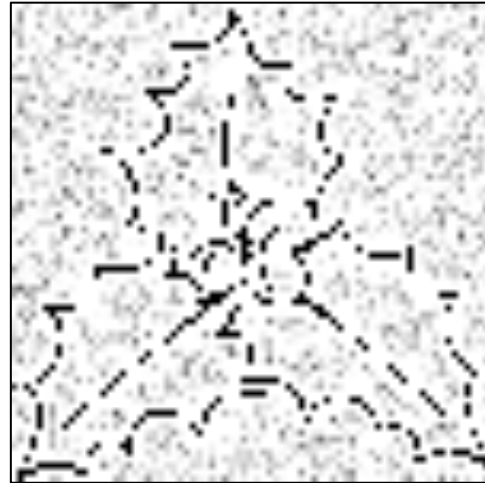


(b) 4x Down

# Anti-aliasing



(a) Input

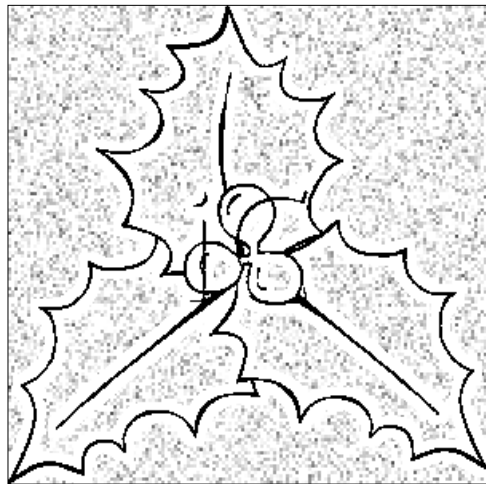


(b) 4x Down

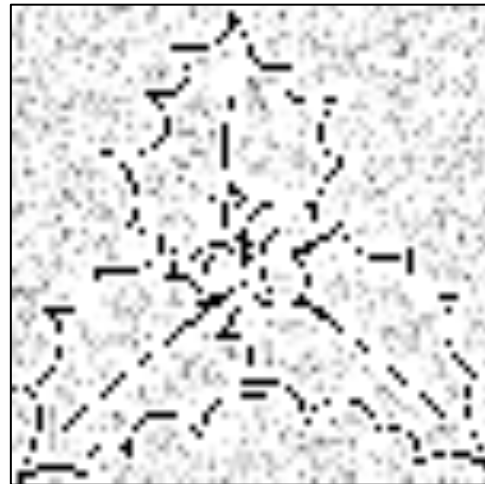


(c) Gaussian+4x Down

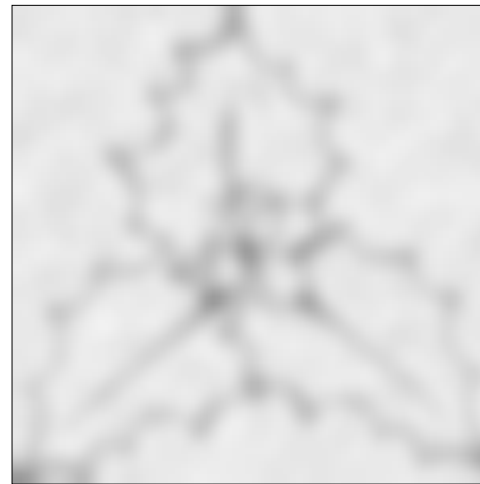
# Adaptive Anti-aliasing



(a) Input



(b) 4x Down



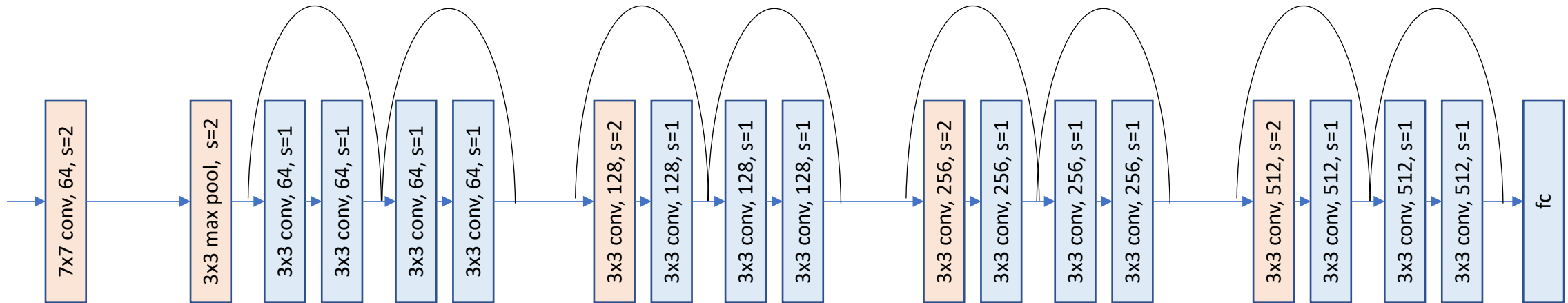
(c) Gaussian+4x Down



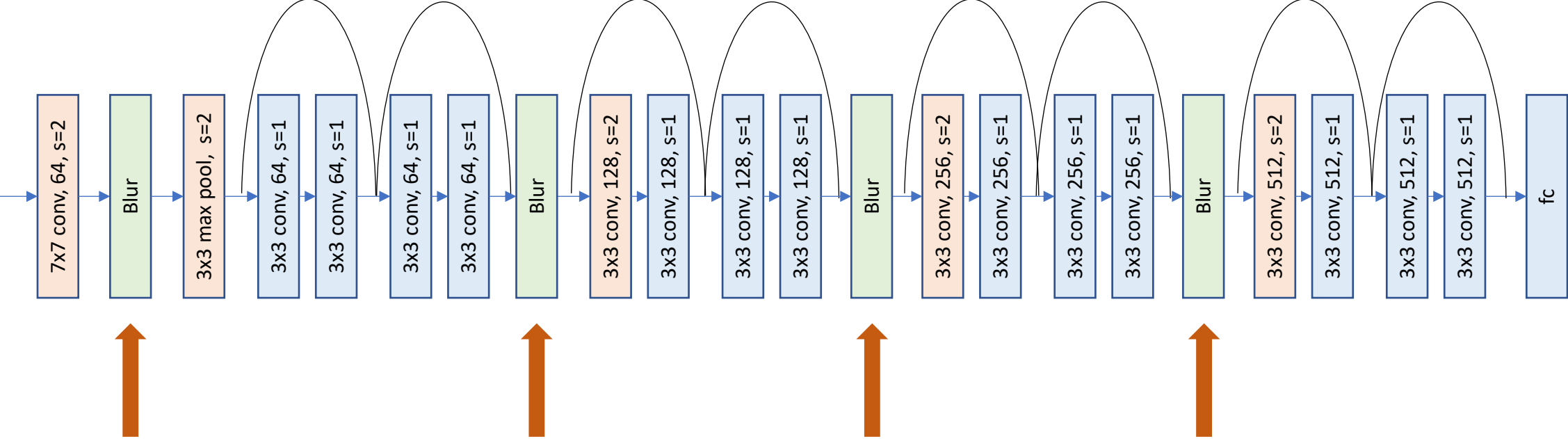
(d) Adaptive+4x Down



# Anti-aliasing in ConvNets: ResNet 18



# Anti-aliasing in ConvNets: ResNet 18



[1] Making Convolution Network Shift and Invariant Again. Zhang. *ICML 2019*

# Fixed **vs** Spatially-Adaptive Low-pass filter

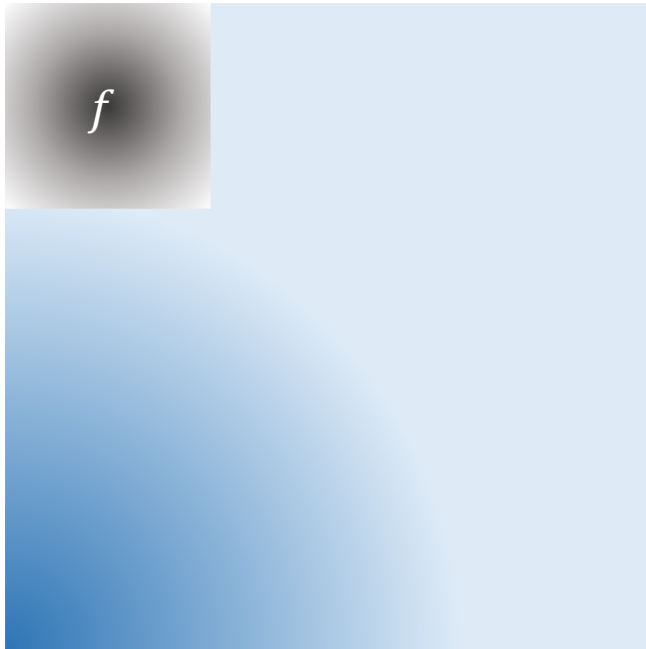


(a) Fixed Lowpass Filter [1]



(b) Adaptive Lowpass Filter

# Fixed **vs** Spatially-Adaptive Low-pass filter

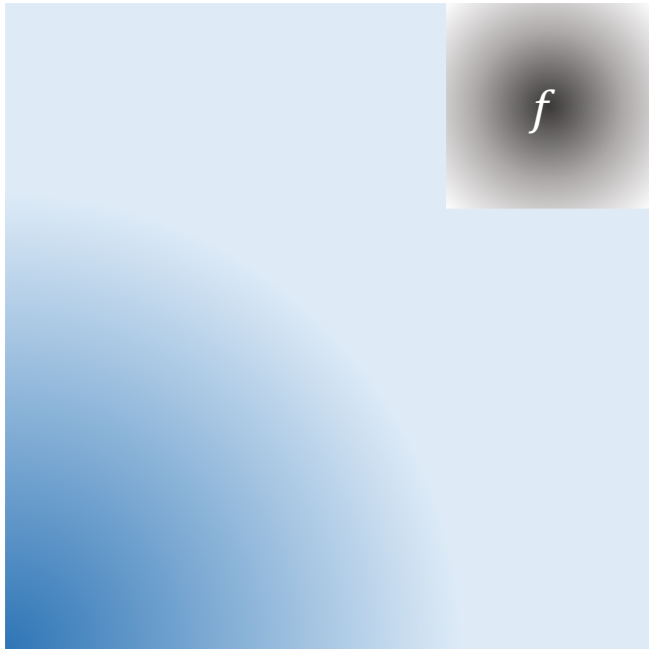


(a) Fixed Lowpass Filter [1]



(b) Adaptive Lowpass Filter

# Fixed **vs** Spatially-Adaptive Low-pass filter



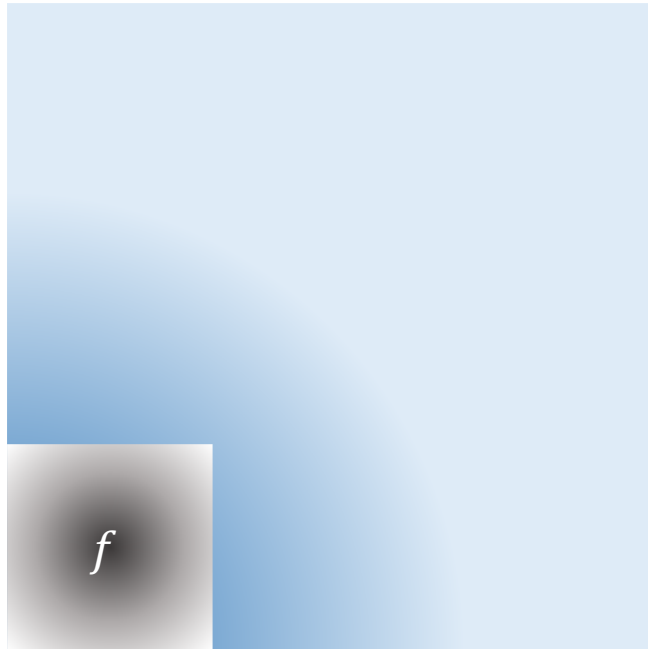
(a) Fixed Lowpass Filter [1]



(b) Adaptive Lowpass Filter



# Fixed **vs** Spatially-Adaptive Low-pass filter

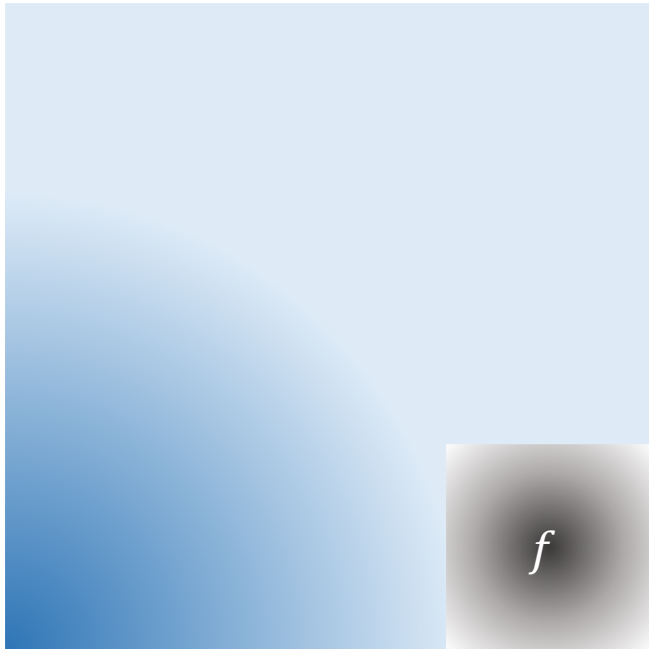


(a) Fixed Lowpass Filter [1]



(b) Adaptive Lowpass Filter

# Fixed **vs** Spatially-Adaptive Low-pass filter

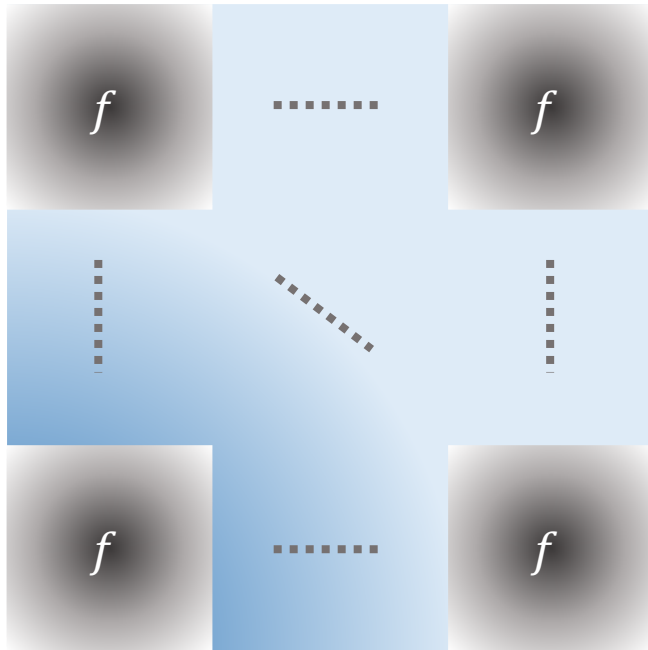


(a) Fixed Lowpass Filter [1]



(b) Adaptive Lowpass Filter

# Low-pass Filter vs Spatial Adaptive Low-pass filter

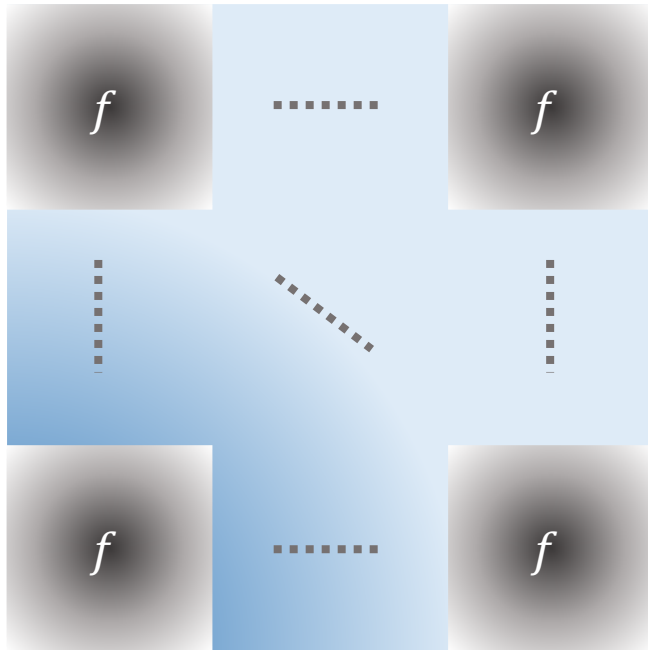


(a) Fixed Lowpass Filter [1]

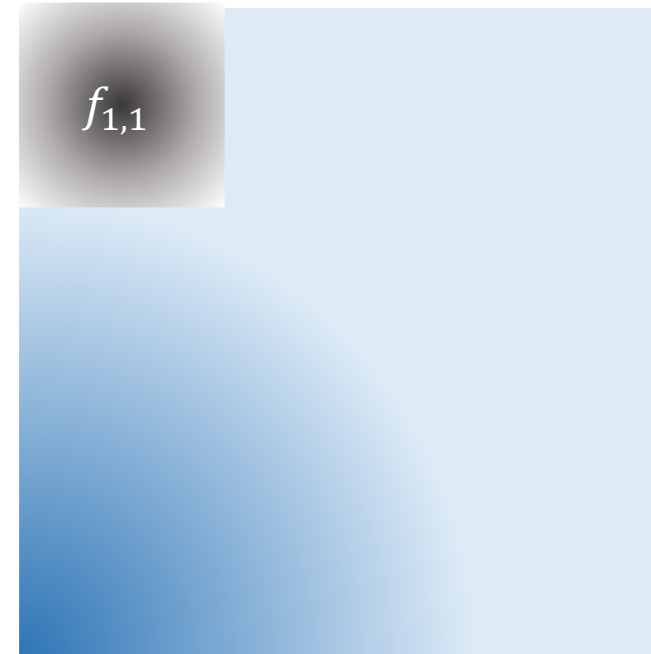


(b) Adaptive Lowpass Filter

# Fixed vs Spatially-adaptive Low-pass filter

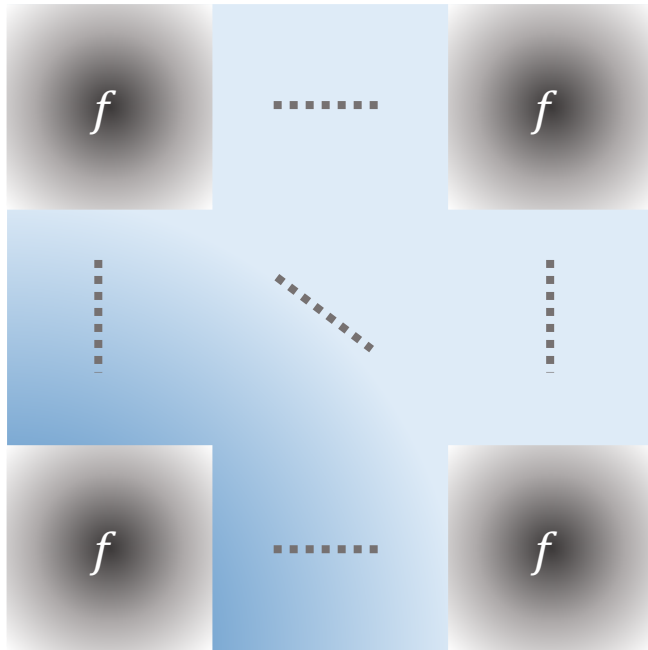


(a) Fixed Lowpass Filter [1]



(b) Adaptive Lowpass Filter

# Fixed vs Spatially-adaptive Low-pass filter



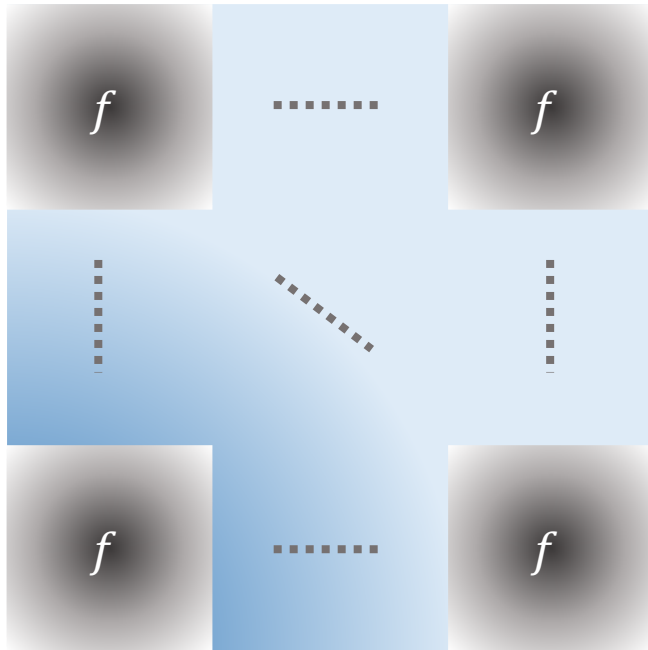
(a) Fixed Lowpass Filter [1]



(b) Adaptive Lowpass Filter



# Fixed **vs** Spatially-adaptive Low-pass filter

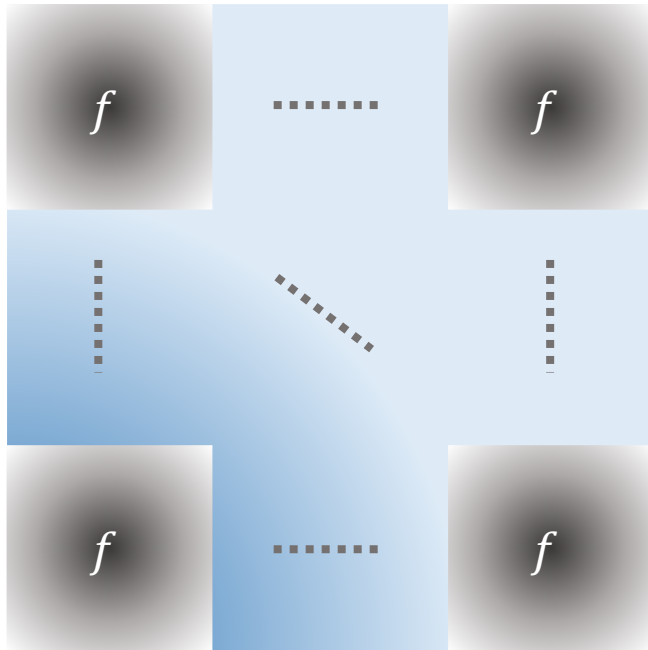


(a) Fixed Lowpass Filter [1]

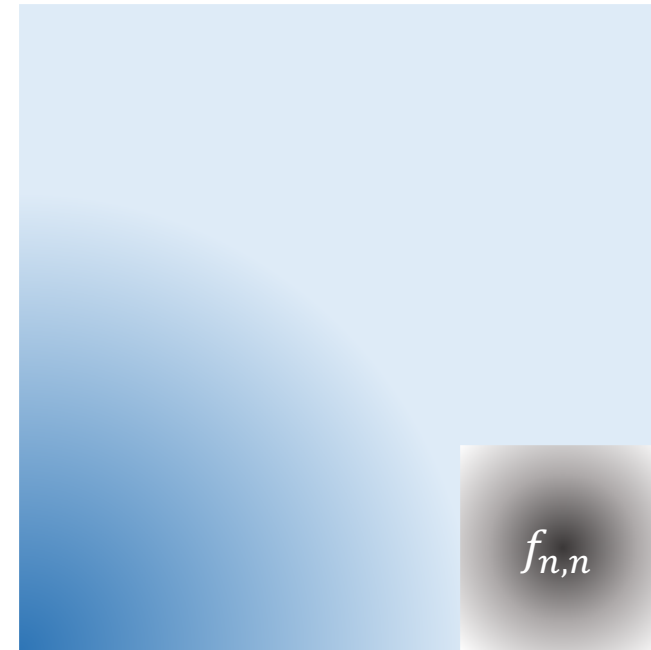


(b) Adaptive Lowpass Filter

# Fixed **vs** Spatially-adaptive Low-pass filter

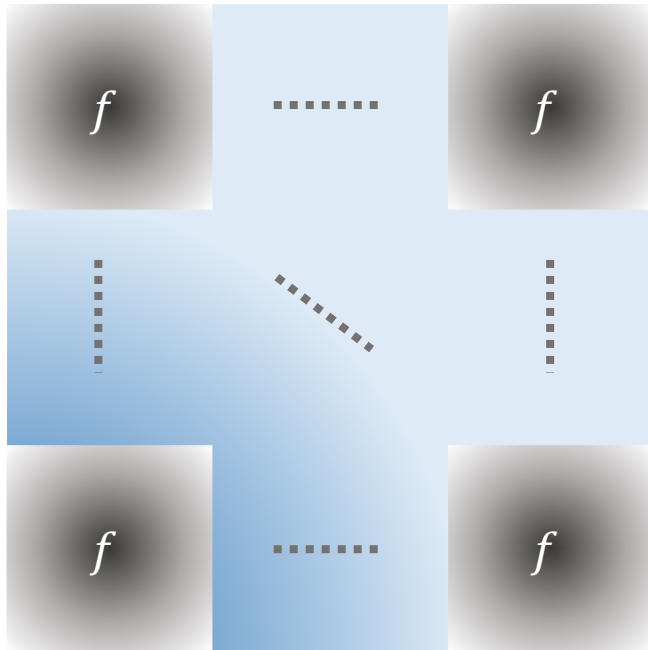


(a) Fixed Lowpass Filter [1]

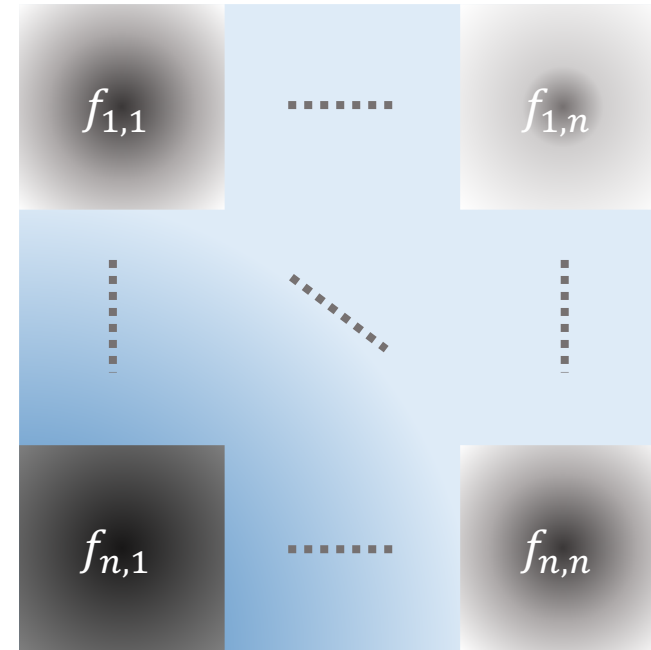


(b) Adaptive Lowpass Filter

# Low-pass Filter vs Spatial Adaptive Low-pass filter

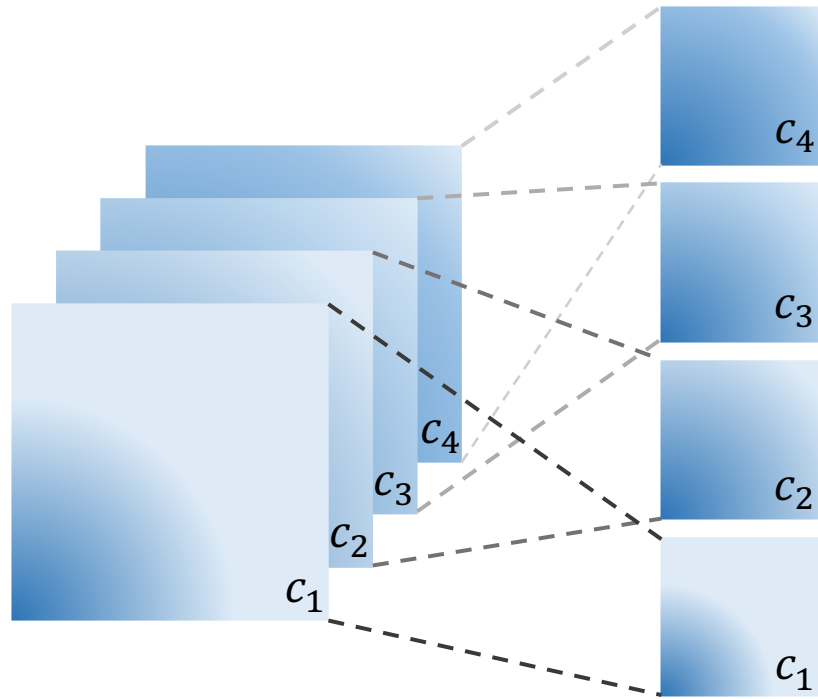


(a) Fixed Lowpass Filter [1]



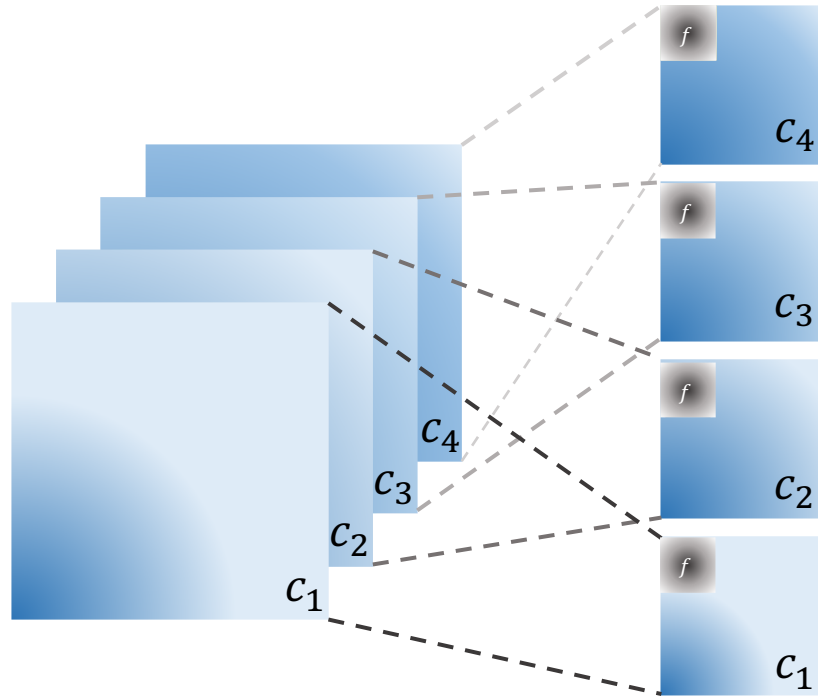
(b) Adaptive Lowpass Filter

# Fixed **vs** Channel Adaptive Low-pass filter



(a) Fixed Lowpass Filter [1]

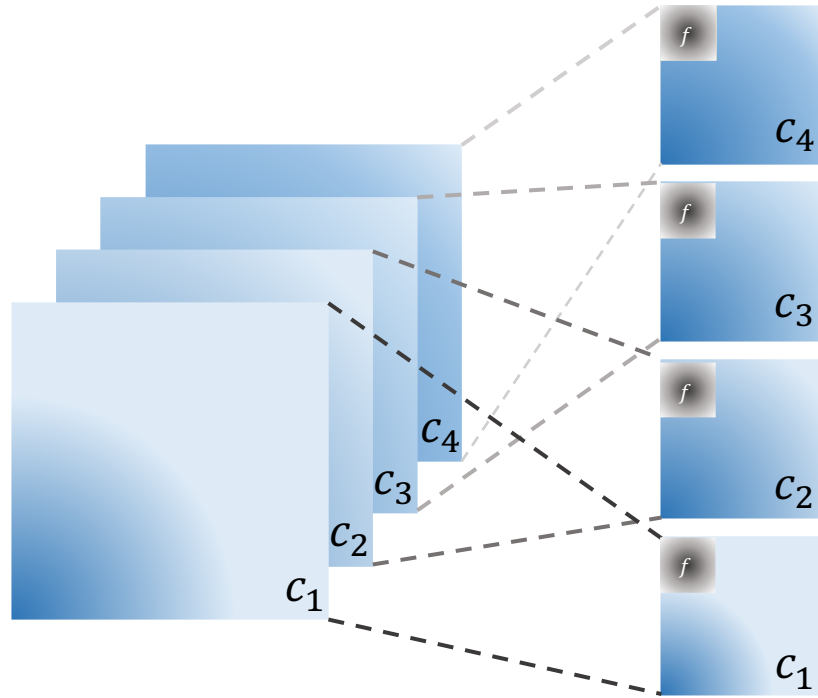
# Fixed **vs** Channel Adaptive Low-pass filter



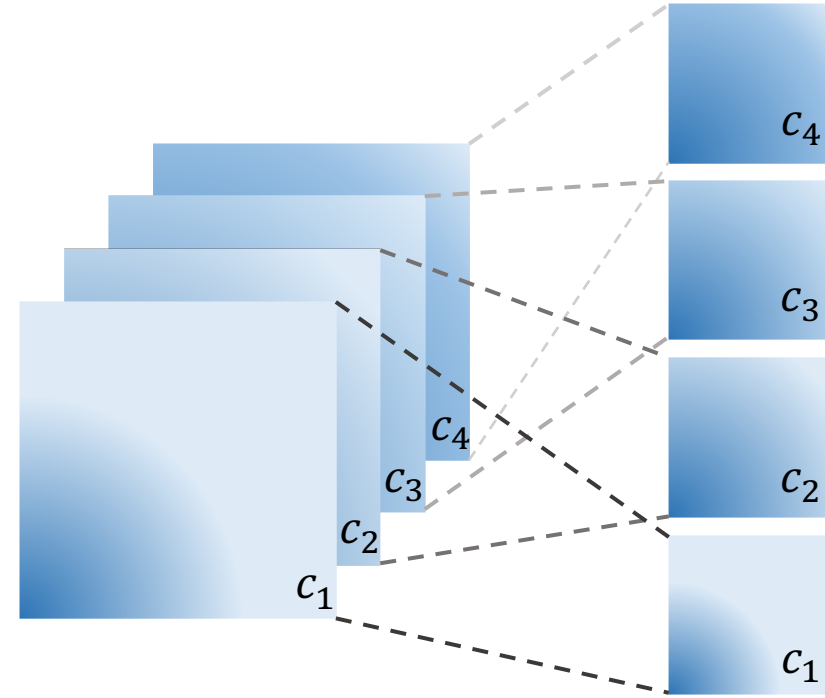
(a) Fixed Lowpass Filter [1]



# Fixed vs Channel Adaptive Low-pass filter

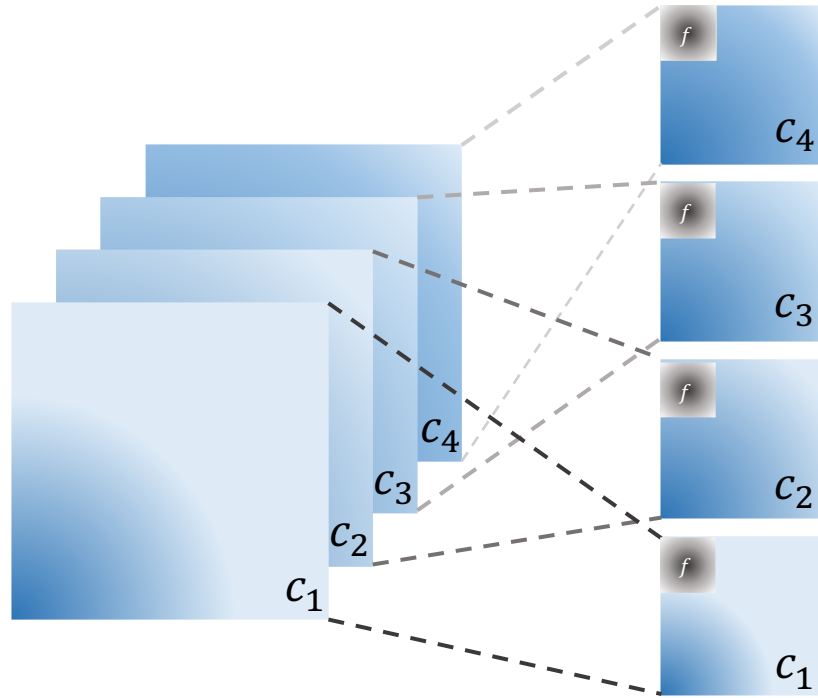


(a) Fixed Lowpass Filter [1]

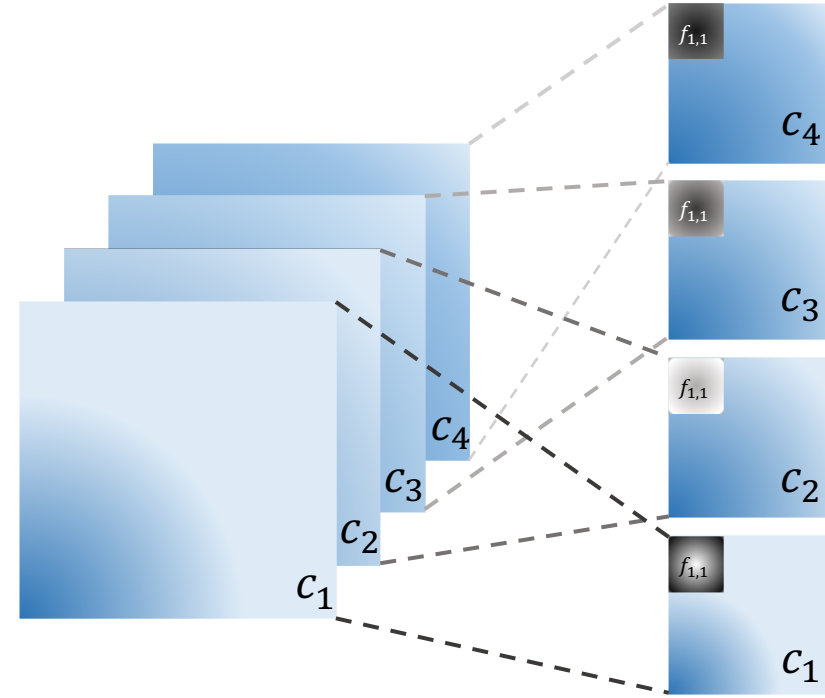


(b) Adaptive Lowpass Filter

# Fixed vs Channel Adaptive Low-pass filter

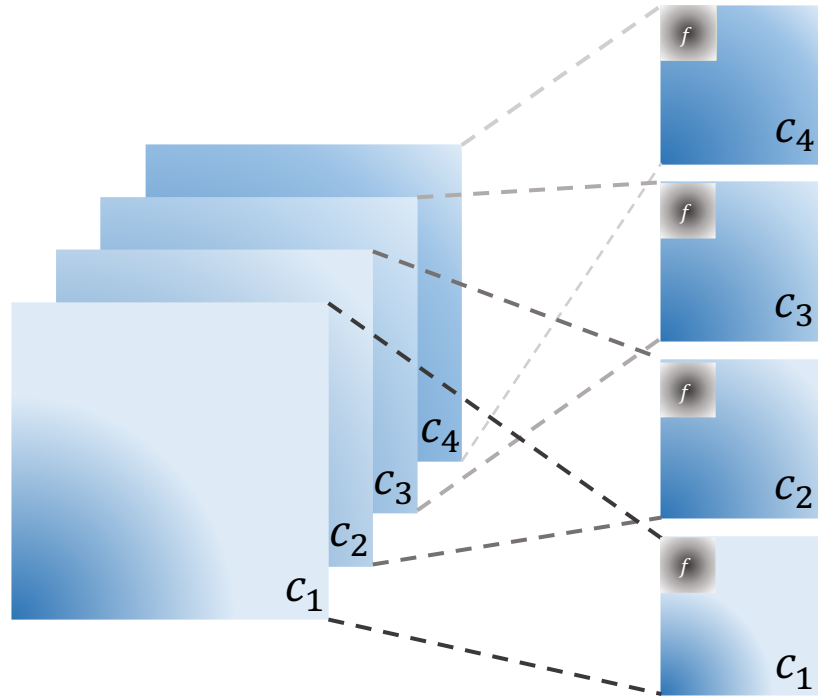


(a) Fixed Lowpass Filter [1]

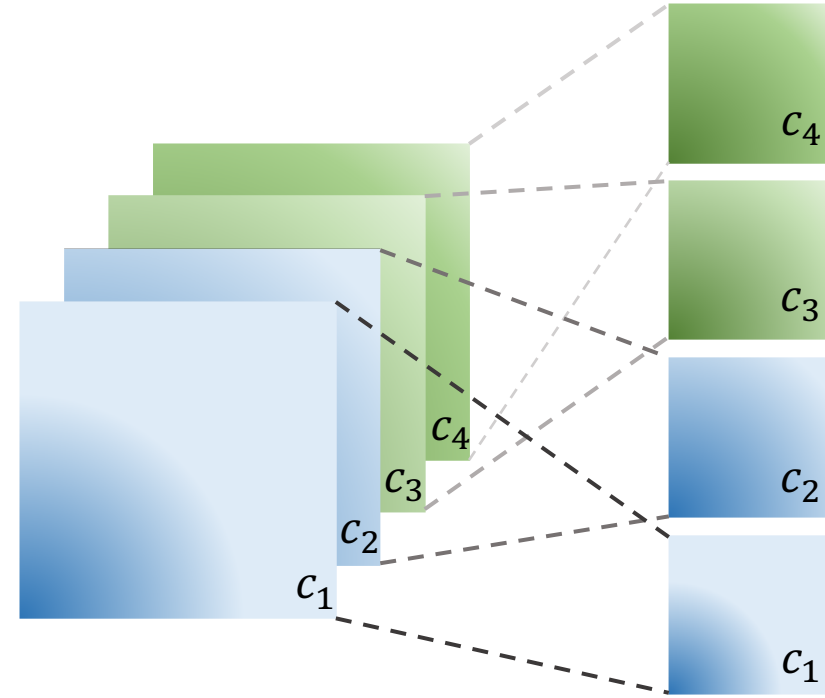


(b) Adaptive Lowpass Filter

# Fixed **vs** Group Adaptive Low-pass filter

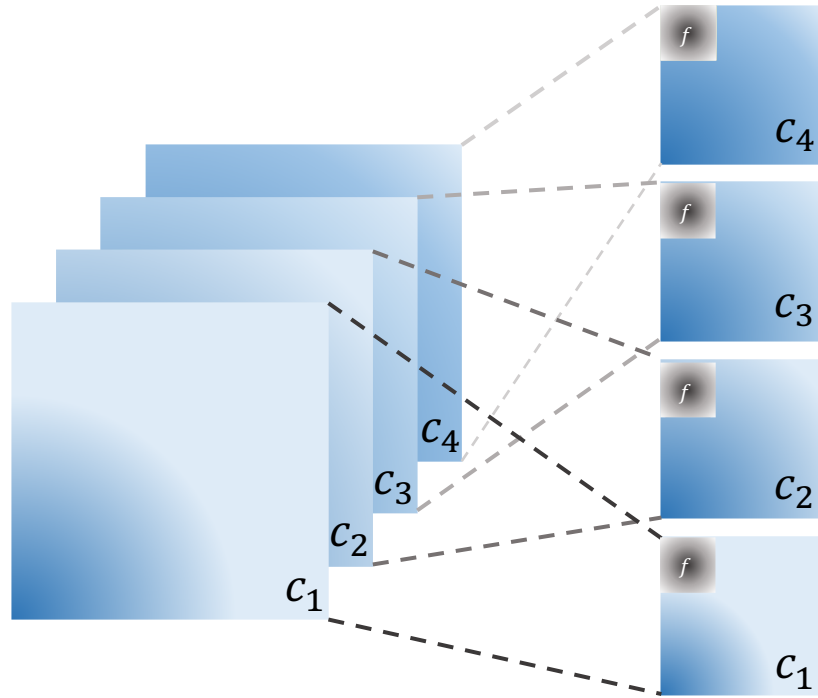


(a) Fixed Lowpass Filter [1]

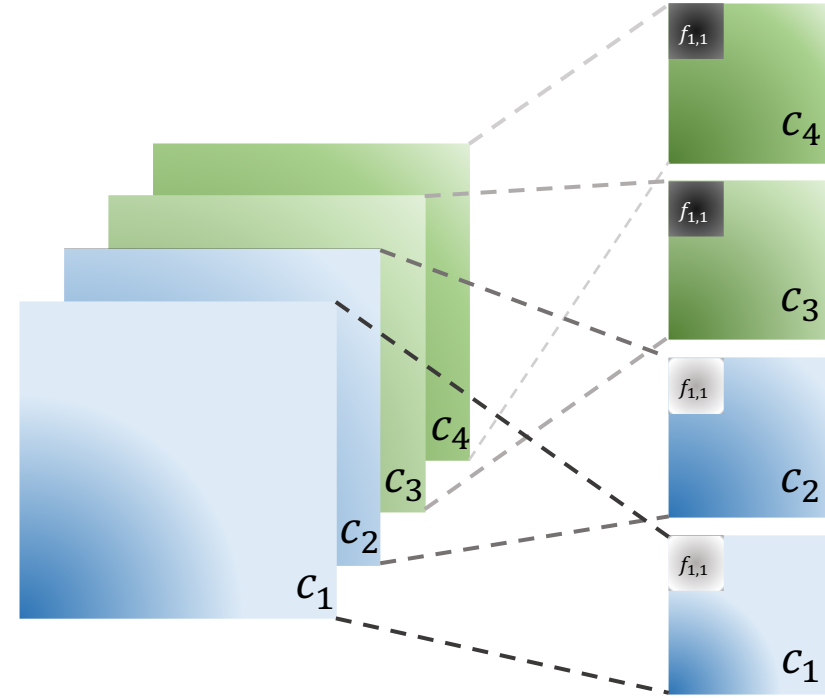


(b) Adaptive Lowpass Filter

# Fixed **vs** Group Adaptive Low-pass filter

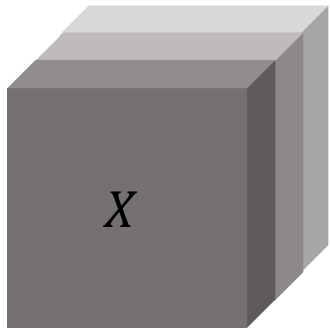


(a) Fixed Lowpass Filter [1]



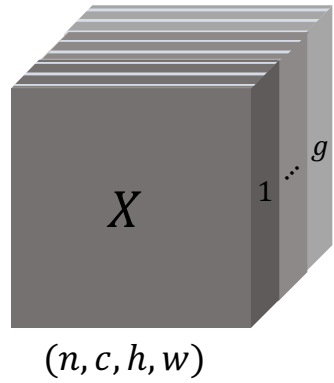
(b) Adaptive Lowpass Filter

# Method Overview

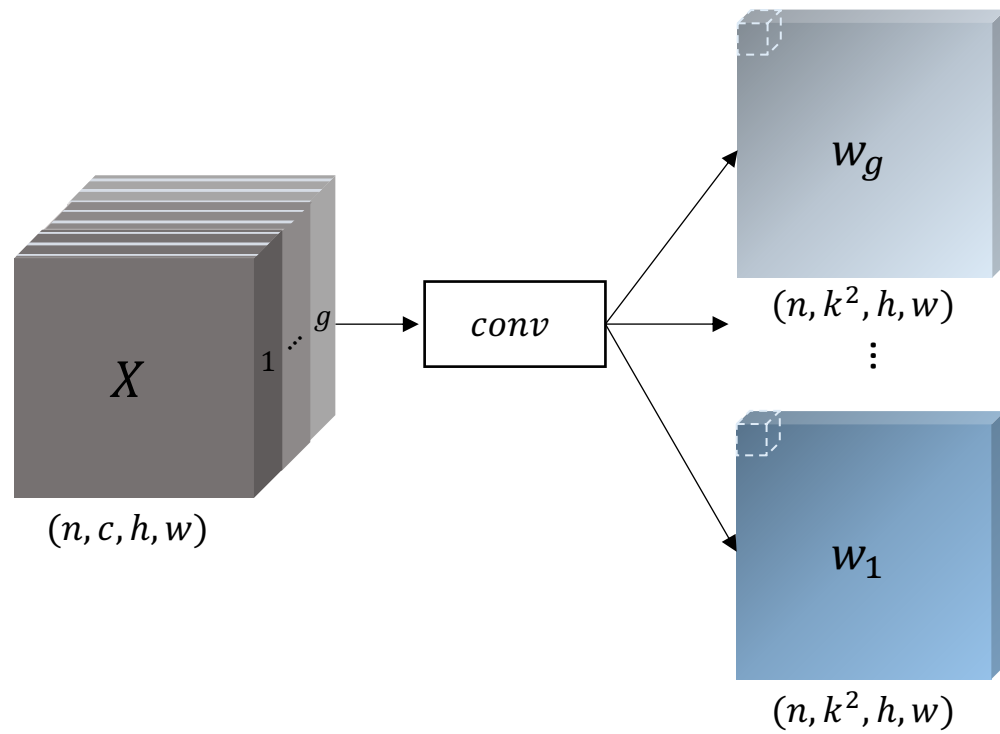


$(n, c, h, w)$

# Method Overview

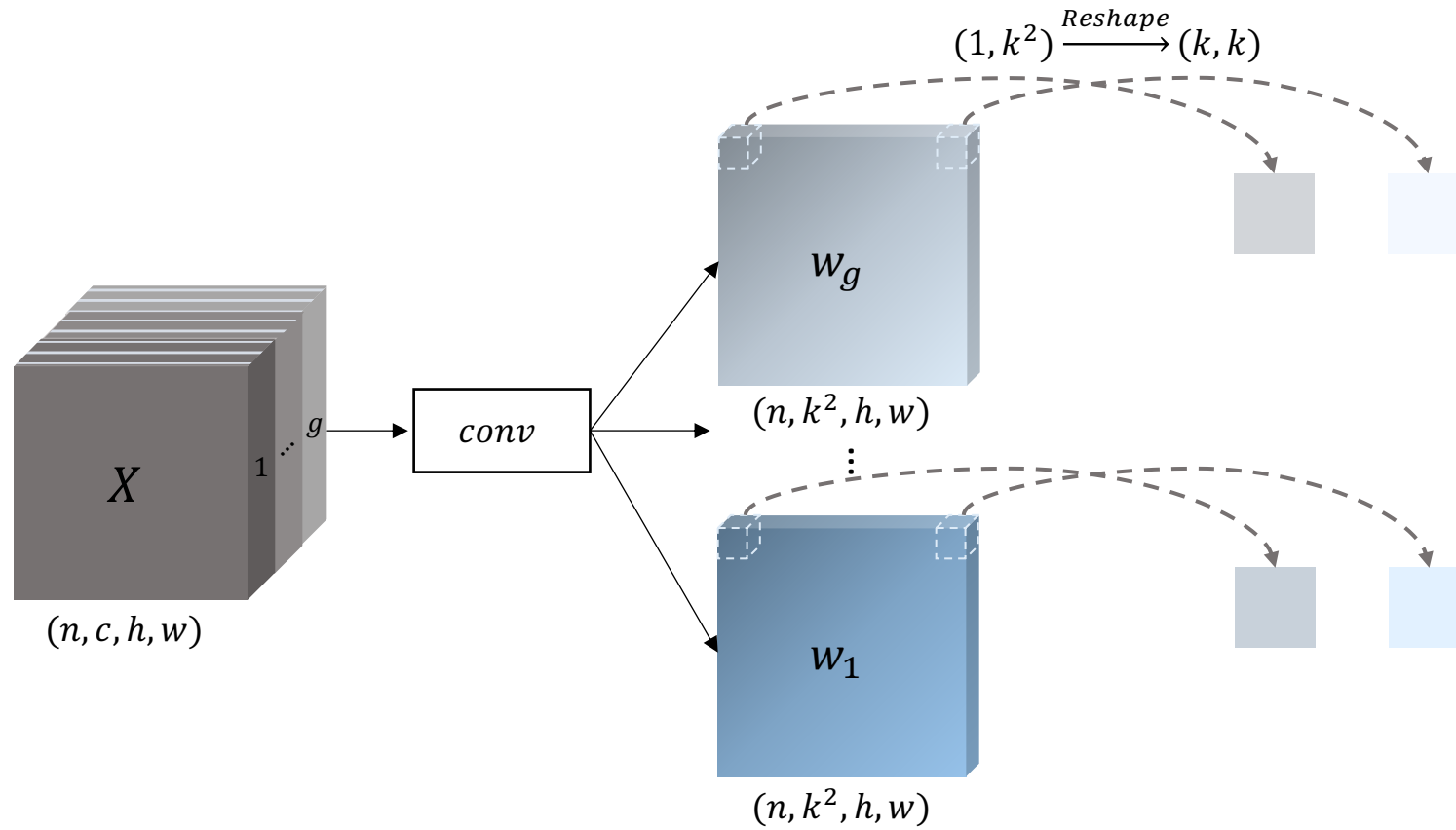


# Method Overview

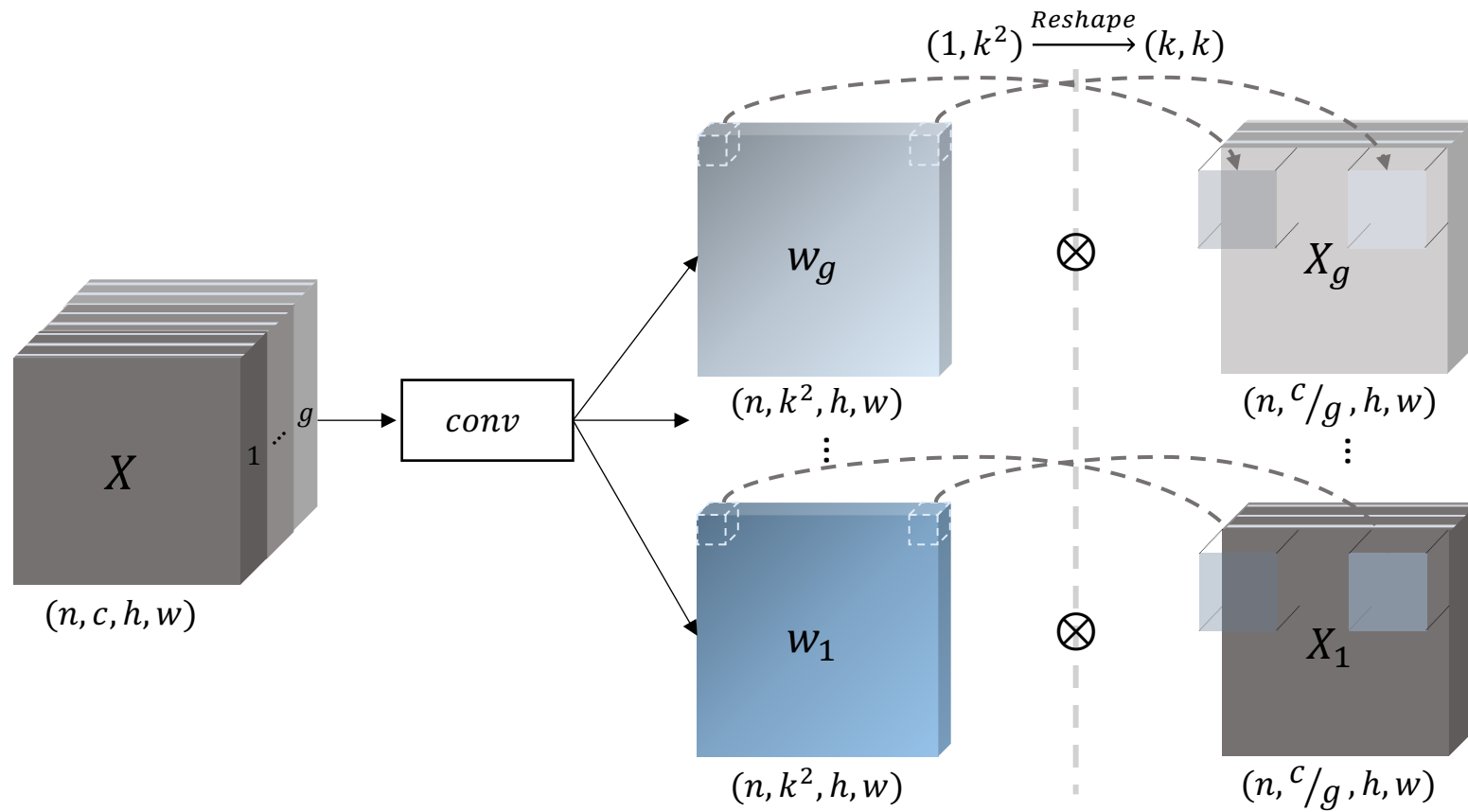




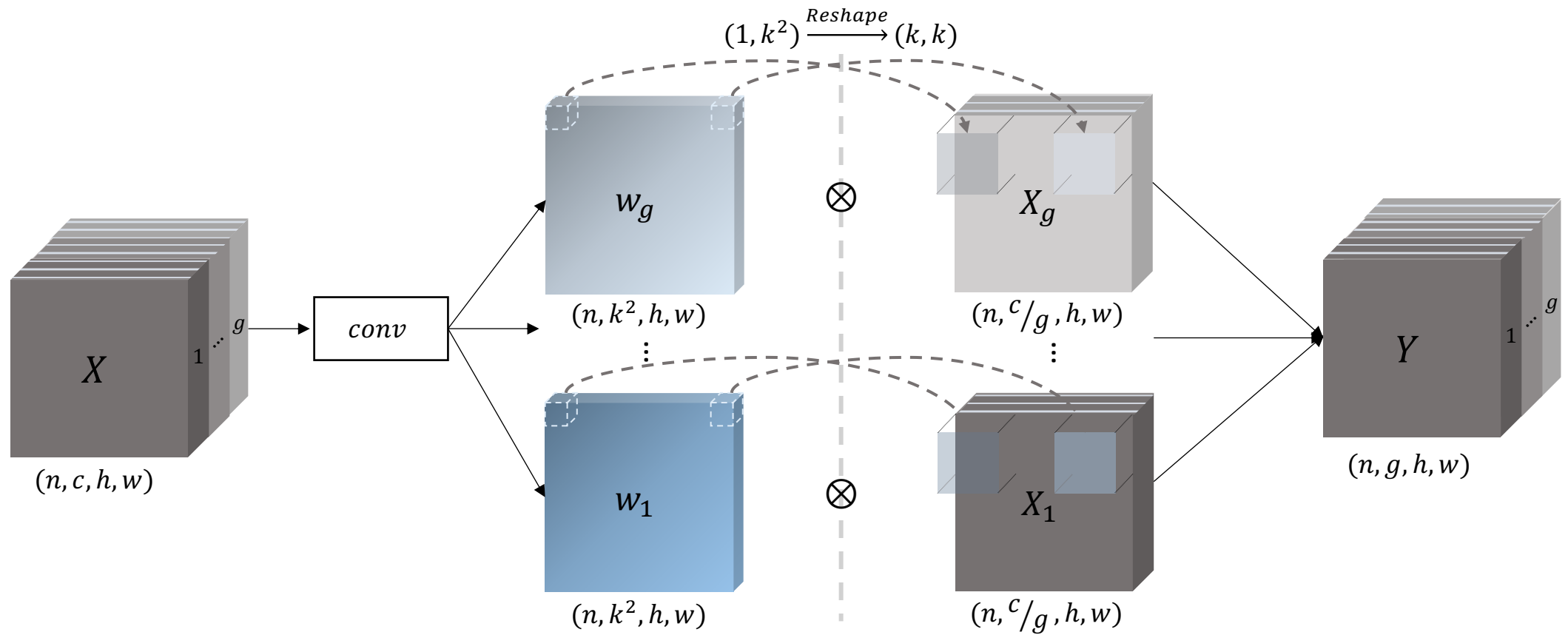
# Method Overview



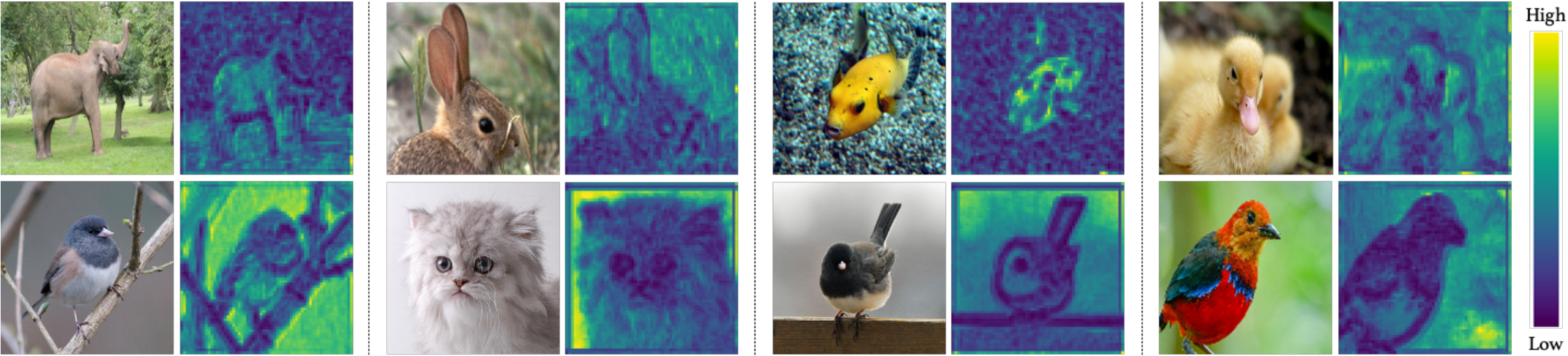
# Method Overview



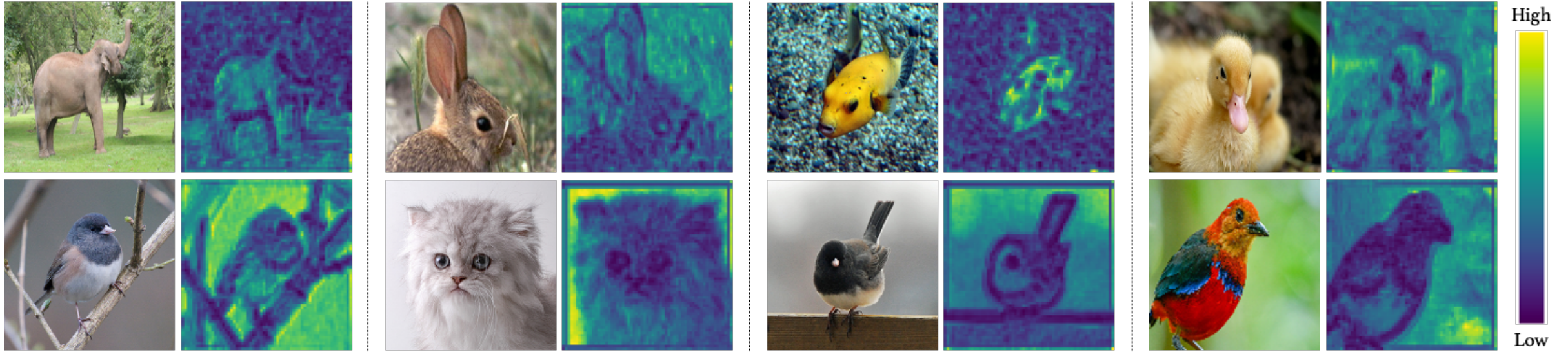
# Method Overview



# Learned Spatial Filter



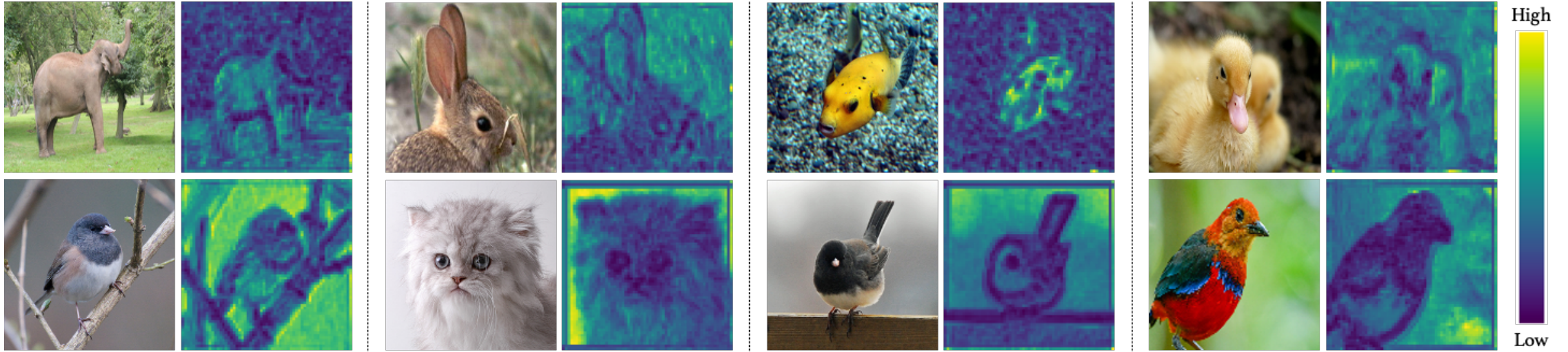
# Learned Spatial Filter



Average Filter:  $Var\left(\begin{array}{|c|c|c|} \hline 1 & 1 & 1 \\ \hline 1 & 1 & 1 \\ \hline 1 & 1 & 1 \\ \hline \end{array} / 9\right) = 0 \quad \leftarrow \text{Low Variance}$



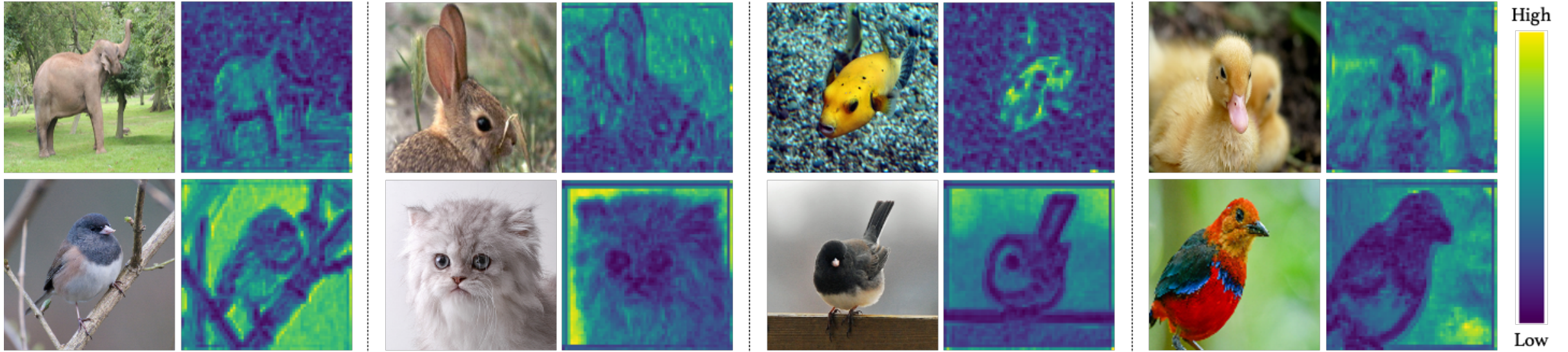
# Learned Spatial Filter



Average Filter:  $Var\left(\begin{array}{|c|c|c|} \hline 1 & 1 & 1 \\ \hline 1 & 1 & 1 \\ \hline 1 & 1 & 1 \\ \hline \end{array} / 9\right) = 0$  <- Low Variance

Identity Filter:  $Var\left(\begin{array}{|c|c|c|} \hline 0 & 0 & 0 \\ \hline 0 & 1 & 0 \\ \hline 0 & 0 & 0 \\ \hline \end{array}\right) = 0.11$  <- High Variance

# Learned Spatial Filter



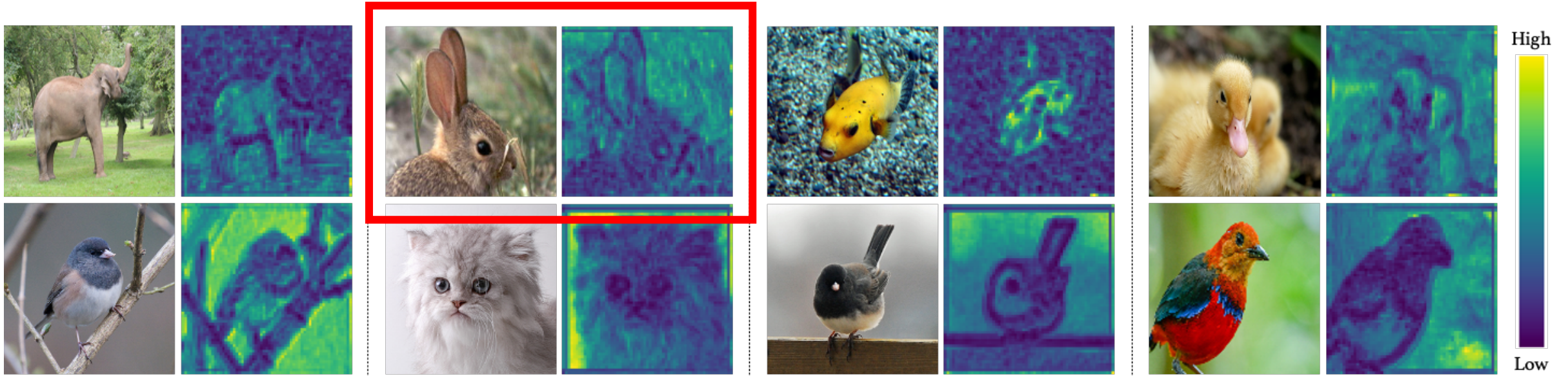
Average Filter:  $Var\left(\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} / 9\right) = 0$  <- Low Variance

Identity Filter:  $Var\left(\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}\right) = 0.11$  <- High Variance

Our model correctly learns to blur high frequency content more to prevent aliasing, and blur low frequency content less to preserve useful information



# Learned Spatial Filter



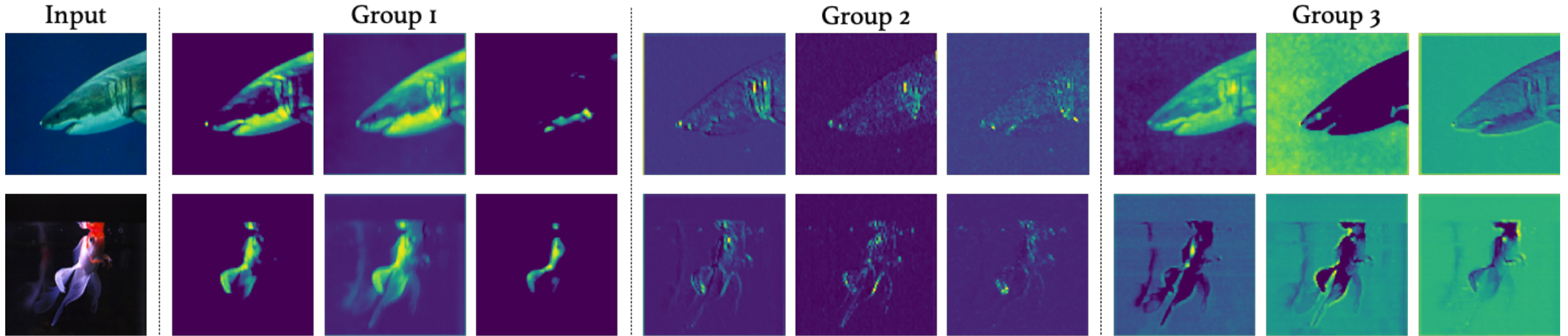
Average Filter:  $Var\left(\begin{array}{|c|c|c|} \hline 1 & 1 & 1 \\ \hline 1 & 1 & 1 \\ \hline 1 & 1 & 1 \\ \hline \end{array} / 9\right) = 0$  <- Low Variance

Identity Filter:  $Var\left(\begin{array}{|c|c|c|} \hline 0 & 0 & 0 \\ \hline 0 & 1 & 0 \\ \hline 0 & 0 & 0 \\ \hline \end{array}\right) = 0.11$  <- High Variance

Our model correctly learns to blur high frequency content more to prevent aliasing, and blur low frequency content less to preserve useful information

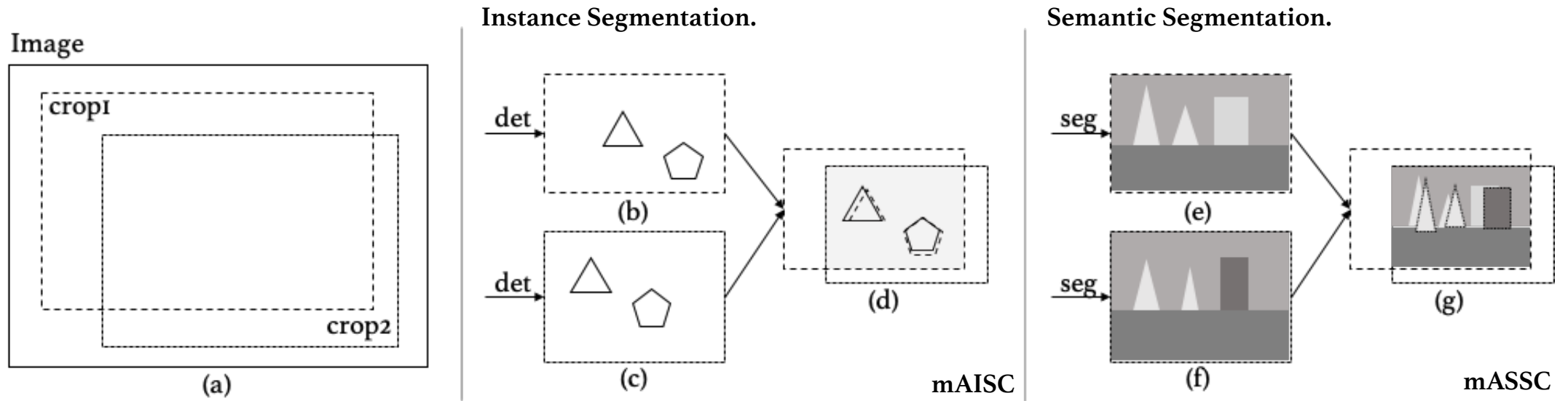


# Learned Group Feature



Features within each group are more similar to each other than those in other groups

# Consistency Metric

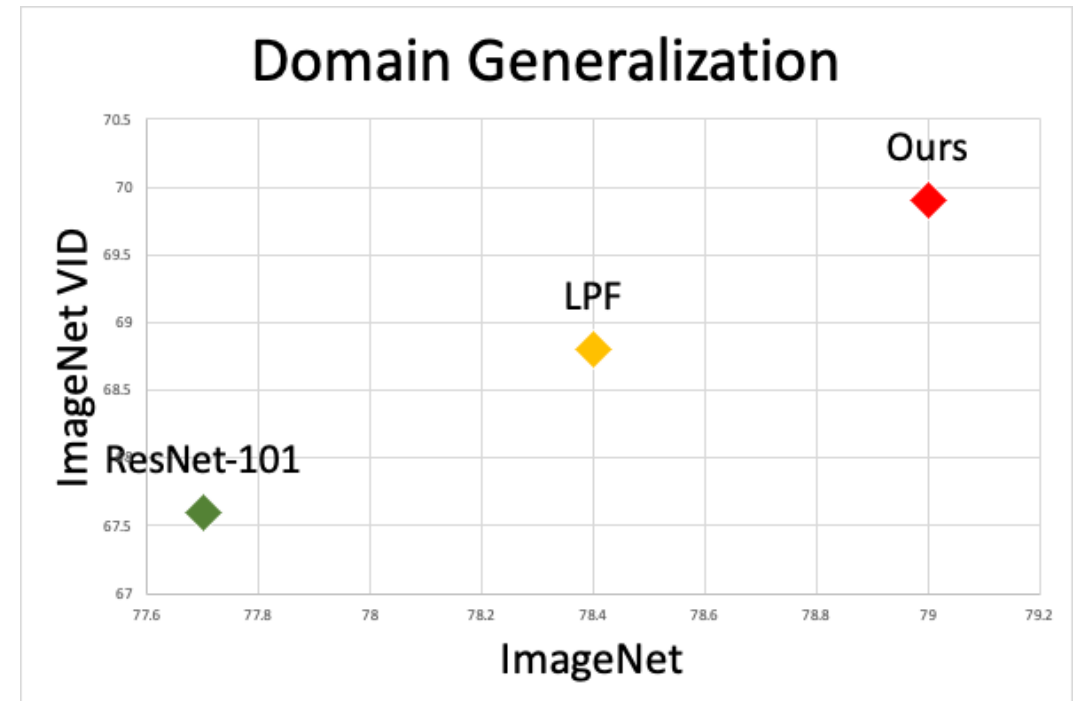
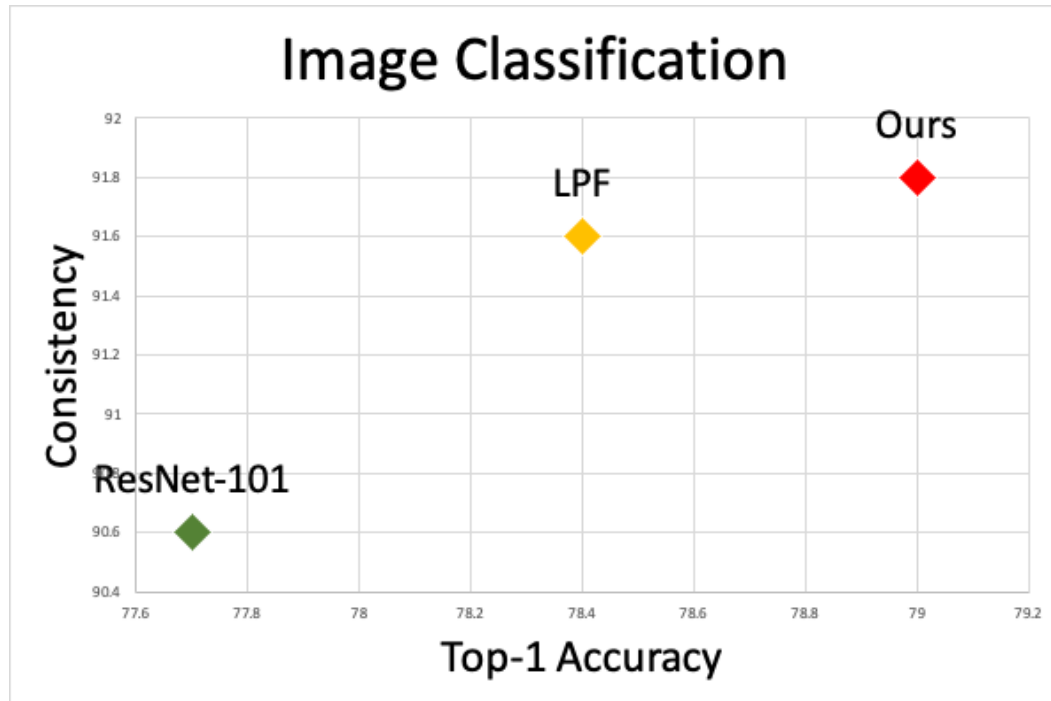


We measure the prediction similarity on the overlapping region of two shifted inputs

# Experiment Results

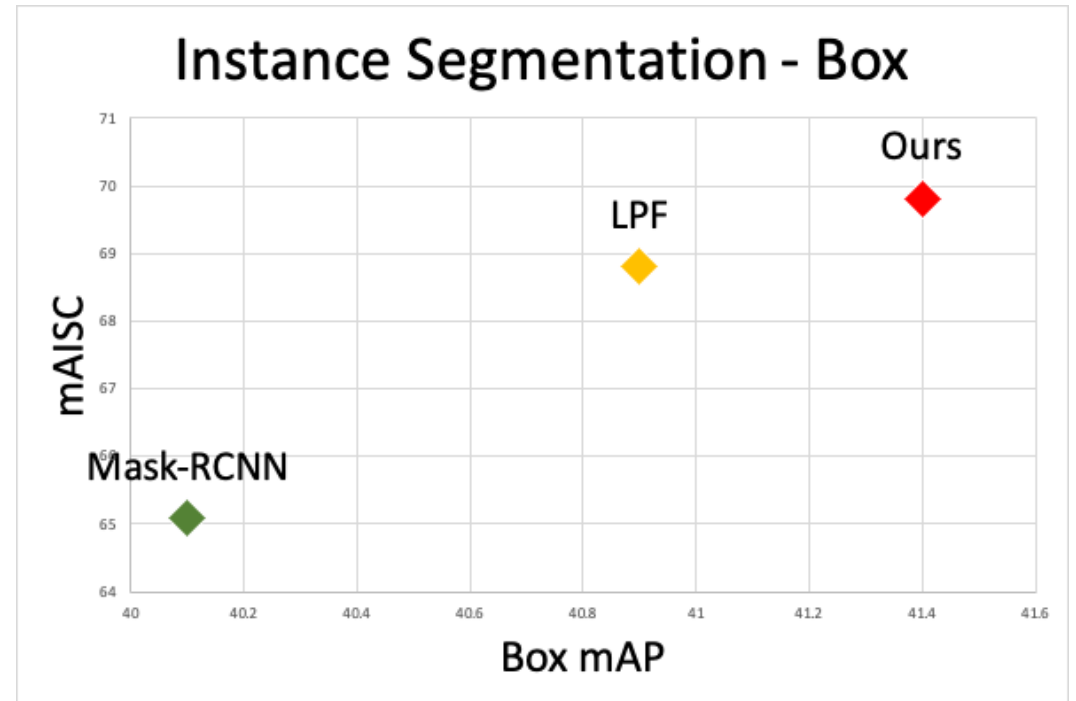
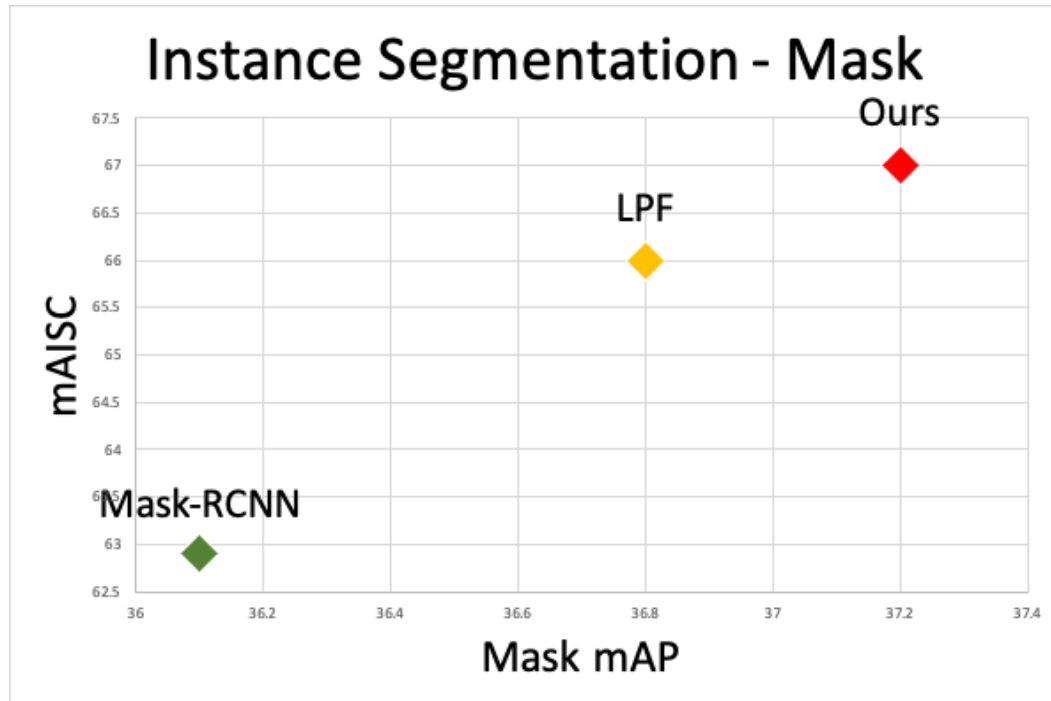
- **Image Classification:** ImageNet
- **Domain Generalization:** ImageNet -> ImageNet VID
- **Instance Segmentation:** COCO
- **Semantic Segmentation:** PASCAL VOC, Cityscape

# Experiment Results



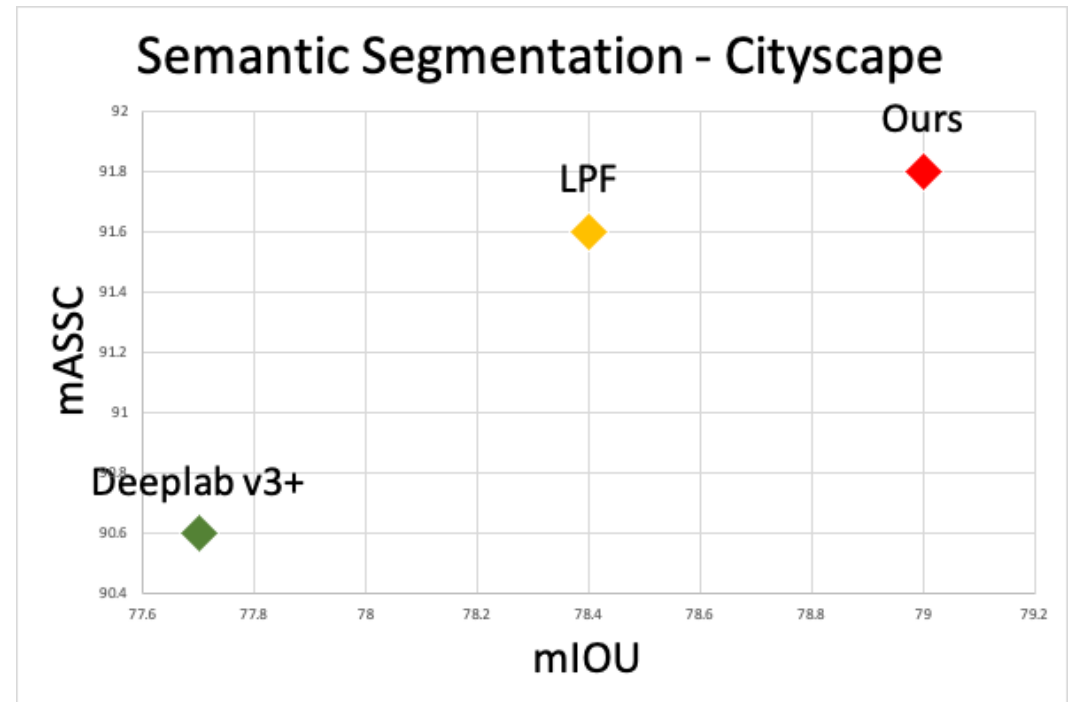
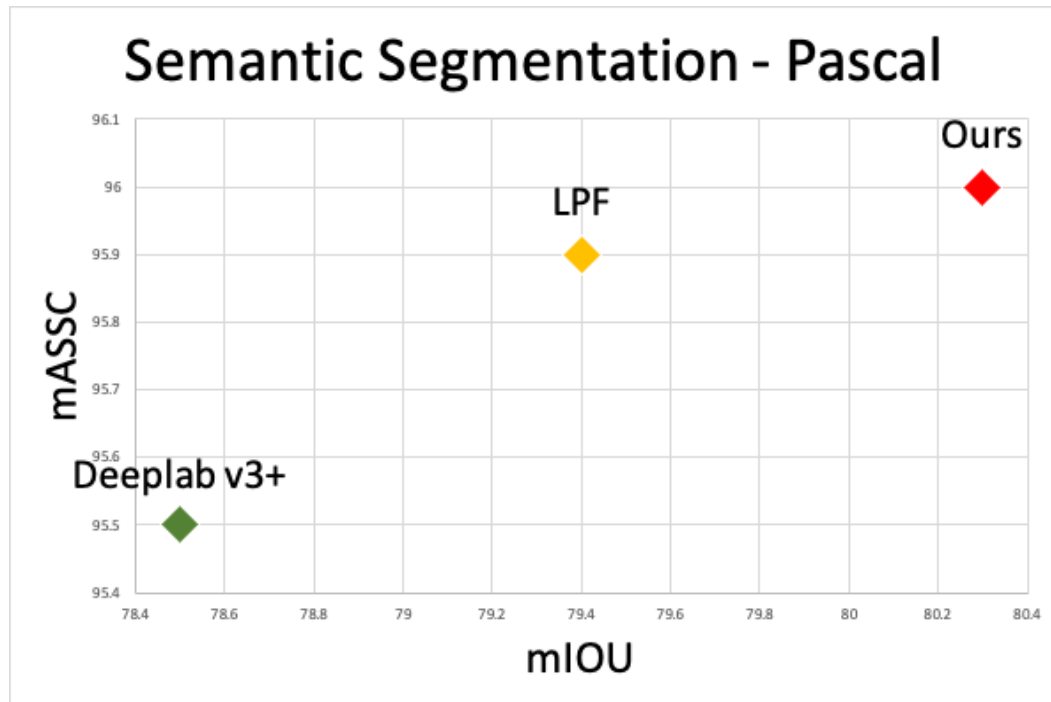
Our method outperforms ResNet-101 and LPF [1] on both accuracy and consistency

# Experiment Results



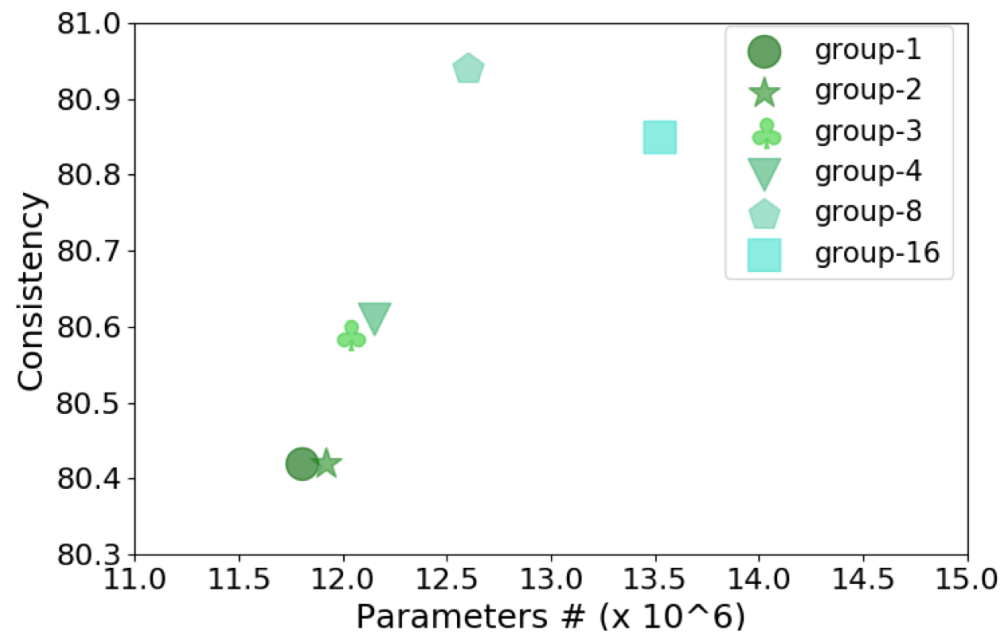
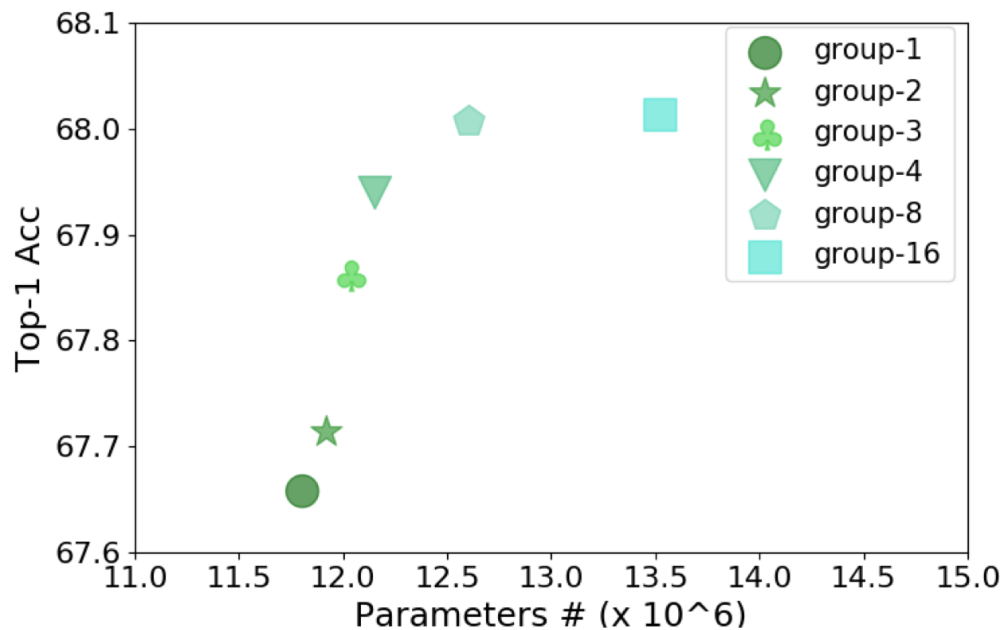
All anti-aliasing techniques improve instance segmentation consistency and accuracy with a large margin

# Experiment Results



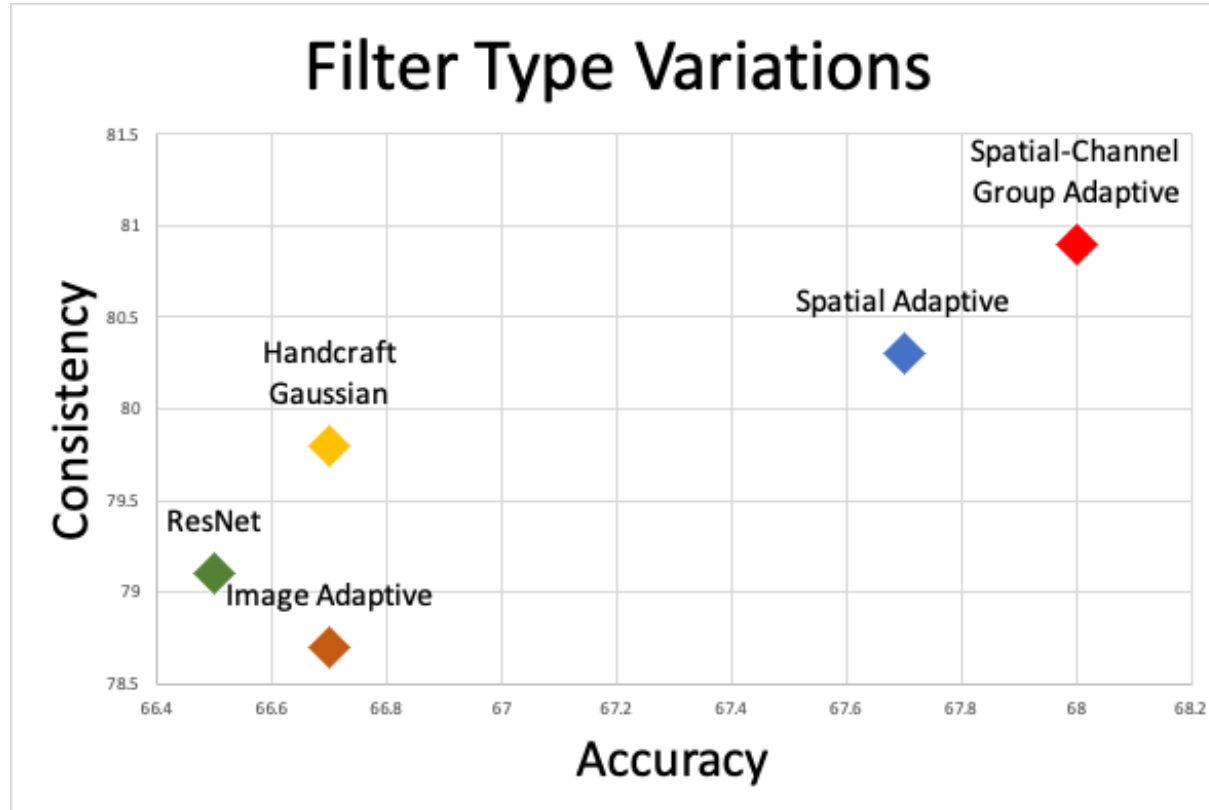
Our method surpass baseline using mIOU metric with 2 points on PASCAL VOC and 1 point on Cityscape

# Ablation Study: Group Number



Top-1 Accuracy saturate with group = 8, where consistency drops when group number > 8

# Ablation Study: Filter Types



Adaptive spatial and channel filtering method will increase both consistency and accuracy with a large margin



# Contributions

- A new adaptive low-pass filtering layer
- New consistency evaluation metrics on pixel classification tasks
- Evaluate our approach on ResNet-101, Mask-RCNN, Deeplab v3+



**Thank You!**